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## Hazard Analysis of Software Requirements Specification for Process Module of FPGA-based Controllers in NPP

Sejin Jung, Eui-Sub Kim, Junbeom Yoo\*, Jong Yong Keum and Jang-Soo Lee

Dependable Software laboratory Konkuk University



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- Introduction
- Software hazard analysis with two approaches
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## Introduction

- Safety systems like nuclear I&C should be identified that hazard or risk in systems are acceptably safe
  - Also, software in these systems should be analyzed before used

Software hazard analysis "... eliminates or controls software hazards and hazards related to interfaces between the software and the system (including hardware and human components). It includes analyzing the requirements, design, code, user interfaces and changes (NIST 1993)

- NUREG/CR-6430 proposes the method for performing software hazard analysis
  - It proposes applicable methods and guide phrases
  - HAZOP is introduced in NUREG/CR-6430 to apply guide phrases



## **Software Hazard Analysis**

- Analysis method in NUREG/CR-6430 had been used in Korea reactor protection systems for PLC development
  - Appropriate guide phrases and analysis process are selected and applied
  - NUREG/CR-6430 provides useful methods is able to be identified
- FPGA has received much attention from nuclear industry as an alternative platform of PLC to digital I&C system
  - FPGA software also should be analyzed before used
  - Using NUREG/CR-6430 methods may be applicable choice

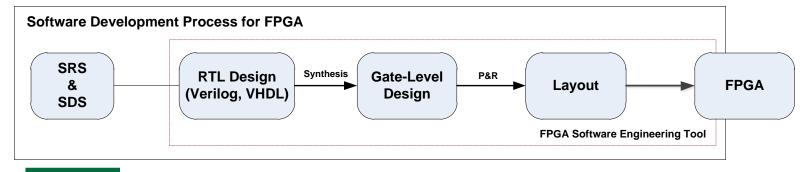


## **Software Hazard Analysis**

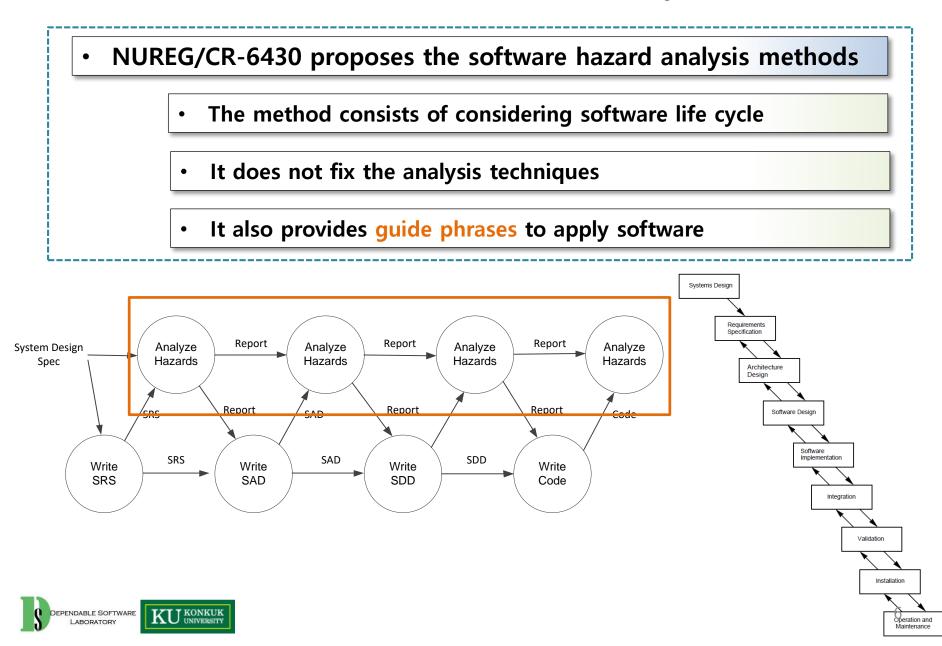
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- However, FPGA has a different development process PLC, since it is a hardware-based platform
  - So, software hazard analysis with NUREG/CR-6430 need to consider the applicability of methods
- We perform the hazard analysis methods of NUREG/CR-6430
  - Target is prototype version of SW requirements specification of module in FPGA-based controllers
  - We perform comparing analysis with analysis results of HAZOP which is applied normal methods



## NUREG/CR-6430: Software Hazard Analysis



## NUREG/CR-6430: Hazard Analysis of Requirements

#### • Prerequisites to software hazard analysis

- Consisting of eight step of process
  - Preparing PHL
  - Performing PHA
  - Assigning consequence level and probability
  - Identifying risk of hazards
  - Identifying requirements specification of system and safety function
  - Prepare a Preliminary Hazard List (PHL) for the application system. This will contain a list of all identified hazards, and will generally be based on the reactor Safety Analysis Report and the list of Postulated Initiating Events (PIE).
  - Prepare a Preliminary Hazard Analysis (PHA) for the application system and subsystems which have impact on the software. This evaluates each of the hazards contained in the PHL, and should describe the expected impact of the software on each hazard.

It is recommended that the PHA assign a preliminary severity level to each hazard. The method outlined in IEC 1226 is acceptable (see Appendix A.1.4 for a discussion). This method assigns a level code of A, B or C to each hazard, where "A" is assigned to the most critical software.

 Carry out the required hazard investigations and evaluations at the application system and application subsystem level. This should include an evaluation of the impact of software on hazards.

- 4. Assign a consequence level and probability of occurrence to each identified hazard. The tables shown in Figures 3 and 4 can be used as a basis for this. These tables are based on IEC 1226 and MilStd 882C, and are discussed in Appendix A.1.4 and A.1.2, respectively.
- Prepare a table like that in Figure 5 from the tables created in step 4. This table can be used to derive an estimate of risk for each hazard.

This table matches the hazard severity categories of Figure 3 to the hazard probability levels of Figure 4 to obtain a measure of overall risk. Thus, events with critical severity and occasional probability of occurrence are judged to have high risk.

 For each hazard identified in the PHL, PHA or other hazard analyses, identify its risk level using the table prepared in step 5.

- Prepare an application system requirements specification.
- Create and document a system design, which shows the allocation of safety functions to software components and other system components and shows how the software component and the remaining application system components will coordinate to address the hazards discovered in previous analyses.
- 9. Prepare the remaining documents to the extent required in order to specify, design, implement, verify and analyze the software component of the RPS. This includes analysis of additional hazards introduced by choice of specific digital hardware, computer language, compiler, software architecture, software design techniques, and design rules. This analysis will be revisited as digital system design and software design are elaborated.

There are at least four potential impacts of software on each hazard (see IEEE 1228, discussed in Appendix A.1.1). These are:

# NUREG/CR-6430: Hazard Analysis of Requirements

- Hazard analysis of software requirements specification
  - It consists of 5 steps
    - Identifying the hazards for software responsible
    - Identifying the critical level
    - Matching each safety-critical requirements in the SRS
    - Analyzing each requirements using the guide phrases
    - Document the results
- Analyzing methods with guide phrases
  - Methods are not fixed

Appendix C. Software Tools for Hazard Analysis .....

- C.1. Fault Tree Analysis
- C.2. FMEA, FMECA, HAZOP
- C.3. Hazard Tracking
- C.4. Markov Chain Modeling
- C.5. Reliability Growth Modeling.....

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#### 3.2. Analysis Procedures

The following steps may be used to carry out the requirements hazard analysis. The steps are meant to help organize the process. Variations in the process, as well as overlap in time among the steps, is to be expected.

- Identify the hazards for which software is in any way responsible. This identification includes an estimate of the risk associated with each hazard.
- Identify the software criticality level associated with each hazard and control category, using the table in Figure 5.
- Match each safety-critical requirement in the software requirements specification (SRS) against the system hazards and hazard categories in order to assign a criticality level to each requirement.
- 4. Analyze each requirement using the guide phrases in Figure 7 which are marked with an "R." These guide phrases are meant to initiate discussion and suggest possibilities to consider, not to bound the analysis.

There are a great many phrases in Figure 7. For any particular requirement, most of these will not apply. For example, only about eight of the phrases would apply to the example given at the beginning of Section 3. Part of the analysis of this step is to select the quality or qualities that apply to the requirement, so that only applicable phrases are used.

5. Document the results of the analysis.

## NUREG/CR-6430: Guide Phrases

### • NUREG/CR-6430 provides guide phrases for applying analysis

- It is able to support analyzing the hazard analysis of SW
- Guide phrases consists of 'quality,' 'aspect,' 'phase' and 'guide phrases'

Quality	Aspect	Phase	Guide Phrases	Aspects of Guide
Accuracy	Sensor	RADC	Stuck at all zeroes	Phrases
		RADC	Stuck at all ones	Fillases
		RADC	Stuck elsewhere	
		RADC	Below minimum range	• Sensor
		RADC	Above maximum range	Actuator
		RADC	Within range, but wrong	Operator
		RADC	Physical units are incorrect	input/output
		RADC	Wrong data type or data size	Calculation
	Actuator	RADC	Stuck at all zeroes	Message
		RADC	Stuck at all ones	• Timing
		RADC	Stuck elsewhere	Functionality
		RADC	Below minimum range	•
		RADC	Above maximum range	
		RADC	Physical units are incorrect	
		RADC	Wrong data type or data size	0



## HAZOP

- HAZOP is used to identify and analyze hazards and operational concerns of a system
  - It utilizes key guide words and system diagrams
  - Generally, HAZOP uses worksheet table to analyze
  - There are several guide words which are used to analyze

			HAZOP guide words							
No.	ltem	Function/Purpose	Parameter	Guide Word	Consequence	Cause	Hazard	Risk	Recommendation	<ul> <li>No</li> <li>Reverse</li> <li>Also</li> </ul>
										• Early
										Late     Part of
										<ul> <li>Before/After</li> <li>Inadvertent</li> </ul>





# SOFTWARE HAZARD ANALYSIS WITH TWO APPROACHES

Software hazard analysis with two approaches to DFLC-N PM SW req.

# Hazard Analysis of FPGA SW requirements

- We use software requirements of DFLC-N PM to analyze
  - SW requirement of DFLC-N PM is the prototype version of FPGA-based controllers in NPPs
  - It consists of 16 component and control software

• Hazard analysis of DFLC-N PM is performed with two approaches

- HAZOP with general worksheet and guide words
- HAZOP with the process of NUREG/CR-6430 and guide phrases
- We identify the usability of NUREG guides by through the analysis



# **Preliminary Hazard List**

- We first identify the preliminary hazard lists of DFLC-N
  - It reflects the characteristics of HW component
  - Consisting of 4 main subjects

No. Preliminary Hazard List – Process M	lodule
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#### Power supply

- a. Loss of operating power
  - b. Over current
  - c. Overvoltage

#### Physical effects of internal/external

- 2 a. Fire occurrence
  - b. Physical impact
    - c. Radioactivity

#### **Operation error**

- a. Operation error of application
- b. Memory error/failure
- c. Response time error(timing error, scan time)
  - d. Error diagnosis function failure
  - e. Lack of transmit capacity
  - f. LED failure

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g. Disability of network

#### **Operation failure**

a. Operation failure by operator (bypass)

## Software Hazard Analysis with NUREG/CR-6430 Guides

- We apply analysis methods of requirements analysis in NUREG/CR-6430 process and guide phrases
  - HAZOP is used to apply guide phrases and analyze
  - Guide phrases are chosen to reflect the characteristics of FPGA
    - Several guide phrases are not used to analyze
  - Perform analyzing relations between PHL and hazards
    - Because, it is able to analyze the effects of higher level of design or design process in software life cycle

Item	Function/ Purpose		Parameter	Guide	Consequence	Hazard
				Phrases		
9.2	Read	and	Read the	Stuck at all	Receive 0 regardless of	Display the normal
Operating	output	the	operating	zeroes	the current state	state when operating
voltage	signal		voltage		Change the state to err	voltage has normal
monitorin			state value		when zero value	value
g function					continues with ten	
					cycles	
				Stuck at all ones	Receive 1 regardless of	Display the error state
					the current state	to a normal state for
					This stuck makes	abnormal operating
					unreached error value	voltage
				Stuck elsewhere	Making opposite state	Display the opposite
					value is possible	state to current
				Below minimum	Do not occur	Х
				range		
				Above minimum	Do not occur	Х
				range		
				Within range,	Making opposite state	Display the opposite
				but wrong	value is possible	state to current
				Physical units	Do not receive any state	Cannot operate
				are incorrect	value by operating	normally with absence
					power monitor	value
				Wrong data	Do not occur	Х
				type or data size		



## Software Hazard Analysis with NUREG/CR-6430 Guides - 2

No Qualities	s Aspects	Item	Function /Purpose	Parameter	Guide Phrases	Deviation	Consequence	Cause		category +	Hazard on SW PHL	Hazard on PM PH								
1 Accuracy	y Sensor	9.2 동작전압감시기 능 하드웨어	동작전압을 감시하여 동작전압감시 기능으로 전달		Stuck at all zeroes	센서의 모든 데이티가 0 으로 stuck 발생	동작전압감시 하드웨어에서 항상 0 전달 10 회 이상 지속 시 err state 변경 -> stuck 으로 인해 전압감시		이상 없는 동작 전압에 대해 err state로 잘못된 상태		1. PM SOFTWARE cannot send qualified	바. LED 점등 S 마. 오류진단 및 기능 오류								
							하드웨어에서 0 값을 향상 전달하기 되고, 요구사항 대로 10회 이상 지속 시 err state 로 번격		변경 -> 정상 동작 중에도 stuck 으로 인하		information of its status									
									잘못된 err state 로 의 변경가능											
2					Stuck at all ones	센서의 모든 데이터가 1 으로 stuck 발생	동작전압감시 하드웨어에서 황상 1 전달 stuck 상태에서 동작전압이상 상황 발생 시 미 전달		동작전압이상에 대해 정상 state 로 잘못된 상태 표시		1. PM SOFTWARE cannot send qualified									
							시 비 선혈		날옷한 강태 표시	1	quaimed information of its status	기동 오류 4. 동작 오류								
3					Stuck elsewhere	센서의 stuck-at fault 가 발생	동작전압감시 하드웨어에서 경우의 다른 전달 가능		동작전압의 현재 상태와 다른 state 로	c	1. PM SOFTWARE cannot send	마. 오류진단 및	오류, 및 감시							
							⇒ stuck 발생으로 인해 0 -> 1 or 0 -> 1 전달 가능		상태 표시		qualified information of its status	기능 오류 4. 동작 오류								
4					Below minimum range	센서에서 범위 아래의 값전달	1bit bookan 값을 전달 받으므로 범위 아레의 값 전달 상황 x		х	-	-									
5					Above minimum range	센서에서 범위 위의 값 전달	⇒ 1 bit 값으로 인해 below, above X 1bit boolean 값을 전달 받으므로 범위 위의 값 전달 상황 x		х		-									
6					Within range, but wrong		동작전압감시 하드웨어에서 상황금 반대의 값 전달	-	동작전압의 현재 상태와 반대되는		1. PM SOFTWARE cannot send	마. 오류진단 9								
									state 상태 표시		qualified information of its status	기능 오류 4. 동작 오류								
7					Physical units are incorrect	센서에 고장 발생	동작전압감시 하드웨어에서 감시 값 미 전달	-	동작전압 상태 표시 값 부재	M 1	1. PM SOFTWARE cannot send	마. 오류진단 및								
									⇒ 하드웨어의 값 미 전달로 인해 출력 값 생성 불가의 가능성 주재		qualified information of its status	기능 오류 4. 동작 오류	-	signal 이 에 정상보다	9.3 ~ 9.10 의 기능에 Clock 신호 늦게 도달		Clock 신호의 늦은 도달로 인한 output 시간 기능 이상 발생	н	3, 4	
8					Wrong data type or data size	센서에서 잘못된 type의 데이터 전달	1bit boolean 값을 전달 받으므로 잘못된 type의 data 전달 상황 x	-	X	-	-			signal 이 에 비정상 도달	Soon, late 와 동일	-	1210 10 20	-		
9	Circuit ⇒ 각 기능 내부의		각 요구사항 별 기능 수행	기능 수행을 위한 계산 회로			잘못된 값 전달 (0으로 stuck 된) 공유메모리에 0으로 stuck 된 값 저장 	-	메모리 감시 기능이 존재 하므로 영향 X	-	-		ie ie	gnal 이 정상	2 번의 scan time 혹은 일정 시간이상 input 이 발생하지 않는 경우 error state로 변경		x		-	
	회로와 관련						전달하려는 값들이 0 으로 stuck 되고 메모리에 저장되는 값도 0 으로 stuc 가능								⇒ error 임을 인지하고 state 를 변경 하기 때문에 req 에서 hazard 는 X					
10					Stuck at all ones	회로의 모든 연결이 1 로 stuck		-	메모리 감시 기능이 존재 하므로 영향 X											
11					Stuck elsewhere	회로에서 stuck 발생	잘못된 값 전달 (stuck 이 발생 한) 공유메코리에 stuck 이 발생 한 값 저장	-	메모리 감시 기능이 존재 하므로 영향 X	-	-			ministic behavior 가 어떻게 되는가	Nondeterministic 존재 X		x	-	-	
						52	_	9.1 ~ 9.11	각 요구사항 별 기능	기능 수행		nt time for operator	동작이 부	족한 시간만이	Reg. memory, output 전달 등의 모든 기능에서 timing 관련 오류 발생 가능 요구사항에서 clock 관련 요구사항 존재		x	-		
						53	Functionality	9.1 ~ 9.10	각 요구사항 별 기능	기능 실행	Function initialized	properly	메모리,		요구사항에서 clock 관련 요구사항 존재 모든 기능에 초기화 요구사항 존재		x	-		
						54	_	콜록신호 생성	Clock 신호 생성	Clock 생성	성 Function out as :	specified (for	기능을 수	수행되지 않는	잘못된 주기의 clock 생성 (80, 20, 10 과 다른)		Clock 이상에 따라 reg,메모리의 timing	н	6. PM SOFTWARE transmit incorrect	가. 연산 오류
						55	_	기능			each operation	mode of	경우가 존 되는가	재하면 어떻게	-	-	관련 이상 발생 Clock 이상에 따라	н	data 3, 4	가. 연산 오류, 라. 용답시간 오류
																	output cycle 기능 이상 발생			다. 응답지간 오유 다. 오류진단 및 감시 기능 오류
						56	_	9.3 ~ 9.10	각 요구사항 별 기능	기능 수행	Function out as : each	specified (for	기능을 수		메모리에 잘못된 결과 writing	-	각 기능별 진단 기능 포함하므로 X	-		
						57	_	9.11	각 요구사항 별 기능	상태 표시		n) is not carried	되는가 Function	이 지정된	System 상태표시 led 에 현재 상태와는		현재 상태와는 다른	м	1. PM SOFTWARE	바. LED 점등 오류,
								상태표시기능				mode of		수행되지 않는 재하면 어떻게	다른 잘못된 결과 전달		LED 점등		qualified information of its	마. 오류진단 및 감시 기능 오류 4. 동작 오류
							_	9.7 입출력 데이터 송수신 및	입출력 데이터 송수신	9.7.4.1		is not carried specified (for			모호한 요구사항 정의로 인해 디자인 단계에서 의도와 다른 디자인 생성	-	불명확한 디자인으로 인해	н	2. PM SOFTWARE transmit incorrect	가. 연산 오류,
								네이터 영무신 및 진단 기능		17	out as : each operation	mode of		수행하지 않는	> 정의된 요구사항의 자연여 모호함으로 인해 디자인 단계와 그 이후에서 요구사항과는 다른 결과 생성		니사인으로 인해 의도하지 않은 signal 발생		transmit incorrect signal	마. 오유신안 및 감기 기능 오류 바. LED 점등 오류 라. 응답시간 오류
						59	_	데이터 송수신 및	데이터링크를 통한 데이 승수신	이티 9.8.4.1 26	out as :	specified (for	function	이 지정한	가능 모호한 요구사항 정의로 인해 디자인 단계에서 의도와 다른 디자인 생성		불명확한 디자인으로 인해	н	2. PM SOFTWARE transmit incorrect	마. 오류진단 및 감/
						_	_	진단 기능			operation		경우가 존				의도하지 않은 signal 발생		signal	기능 오류 바. LED 정동 오류 라. 용답시간 오류
DEPENDA	ABLE SOF		KU KON	KUK		60		9.9 네트워크 데이터 송수신 및 진단 기능		이티 9.9.4.1 36					모호한 요구사항 정의로 인해 디자인 단계에서 의도와 다른 디자인 생성	-	불명확한 디자인으로 인해	н	<ol> <li>PM SOFTWARE transmit incorrect signal</li> </ol>	가. 연산 오류, 마. 오류진단 및 감사 기능 오류

## Software Hazard Analysis with HAZOP

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- Parts of the results about hazard analysis with HAZOP and guide words with generally used
  - All of items and function in requirements are analyzed(matching) with guide words

ltem	Func	tion	Parameter	Guide	Consequence	Cause	Hazard
	/Purp	oose		Words			
9.2	Read	and	Make output	No(fail)	Cannot change	Counter	Circuit/function
Operating	output	the	err value when		state to err when	failure	errors caused by
voltage	signal		P33GD		operating voltage	Output circuit	Overvoltage
monitorin			variable has		has strange	error	
g function			error value			Sensor failure	
				Reverse	Make output to	P33GD save	Unintended ini
					error value while	memory	operation
					current voltage	failure	Display voltage
					operates normal	Output circuit	error state
						failure	
				Also	-	-	-
				Early	-	-	-
				Late	Change the state	Circuit or	Checking
					value is too late	sensor failure	voltage failure i
							done lately
				Part of	-	-	-
				Before/	-	-	-
				After			
				Inadvert	-	-	-
				ent			

## Software Hazard Analysis with HAZOP - 2

	Function /Purpose	Parameter	Guide Words	(Deviation)	Consequence	Cause	Haz	zard				
	하드웨어 및 유저로부티 외부 신호를 받아 clock 생성	MCLK 에 따라 80, 20, 10 MHZ 주기의 clock	No(fail)	Clock 신호 발생 (output X)	행 X Clock 신호 생성 실패로 이후 동작들의 주기 이상		전달 Clock 이상에 띠 기능 이상 발생					
2조 운영시용 전조를 받아 dock 운영		신호 생성		(		내부 stuck 발생	으로 Clock 이상에 따	약라 reg, 메모리				
			Reverse			인한 오류	의 timing 관련	<u>ଏଟ ଅ</u> ଞ				
			Also (additional									
			unintended operation)									
			Early	Clock 신호가 주기 다 빠지 봐세	보 Clock 에 동기화되는 기 데이티 저막이 빠르게 4		바른 Clock 이상에 띄 기능 이상 발생	라 output cycle				
				Item	Function	Parameter	Guide Words	(Deviation)	Consequence	Cause	Hazard	PHL
			Late	_	/Purpose							
				9.1 리셋 및 물 특신호 생성기능	하드웨어 및 유저로부터 외부 신호를 받아 clock 생성	10 MHZ 주기의 clock	No(fail)	Clock 신호 발생 X (output X)	Clock 신호 생성 실패로 인해 이후 동작들의 주기 이상화		Clock 이상에 따라 output cycle 기능 이상 발생	오류
			Part of			신호 생성				내부 stuck 발생으로 인한 오류	Clock 이상에 따라 reg, 메모리 의 timing 관련 이상 발생	나. 미 리오루 다. 유
			Before/After	_								시간 오
							Reverse					
			Inadvertent				Also (additional unintended operation)	-				
	하드웨어 및 유저로부터 의부 신호를 받아 resetsignal 생성	사용자 명령 및 하드 웨어 상태에 따라 resetsignal 발생	No(fail)	_			Early	Clock 신호가 주기보 다 빨리 발생	Clock 에 동기화되는 기능 및 데이티 전달이 빠르게 수행	MCLK 신호의 빠른 입력	Clock 이상에 따라 output cycle 기능 이상 발생 Clock 이상에 따라 reg, 메모리 의 timing 관련 이상 발생	오류 나. 미 리오루
			Reverse									다. 응 시간 S
			Also				Late	Clock 신호가 주기보	Clock에 용기화되는 기능 및	MCLK 신호의 느린	Clock 이상에 따라 output cycle	가. 9
			Early	_				다 늦게 발생	데이터 전달이 늦게 수행	입력	기능 이상 발생 Clock 이상에 따라 reg, 메모리	오류 나. 대
			Late								Clock 이상에 따라 reg, 에오리 의 timing 관련 이상 발생	리 오루 다. 응
			Part of	_			Part of	3 가지 clock 신호 중	-	발생 X		시간 5
			Before/After	_			Before/After	일부분만 발생 Clock 신호가 순서대		발생 X		
			Inadvertent					로 발생 X				
				_			Inadvertent	의도하지 않은 clock 신호 발생				
					하드웨어 및 유저로부터 외부		No(fail)	Reset 입력 시 signal	Reset signal 이 전달되지 않	Reset 요청 input 미	reset되지 못함으로 인해 이후	가. 연상
					신호를 받아 reset signal 생성	웨어 상태에 따라 reset signal 발생		발생 실패	8	전달 내부 stuck 발생으로	reset 진행 X 및 오류 상태 유 지	오류 라. 오루
										인한 오류		진단 및
												감시기
							0	200000 0111 m	THAN 10 TO A140 11	ALC: 1010 2 010	funtan fil maintended anot	오류 가. 연
							Reverse	Reset이 아닐 때 signal 발생	정상 동작 상황 시 reset signal이 발생됨	오류 Stuck 월경도로 인전	System≌  unintended reset	오류 21. 전1
												라. 오
												진단 및
												감시가 오류
							Also	-				
							Early	-				
							Late	Reset signal 이 요청	의도하지 않은 timing (늦은	Clock 이상	System reset이 늦게 발생함으	가. 연
								보다 늦게 발생	주기)에 reset 발생		로 인해 정상보다 다른 타이밍 으로 동작함	오류

Discussion of the results

# **DISCUSSION OF THE RESULTS**



- Difference points of the analysis results about two approaches
  - Guide phrases and perspective makes the differences
  - We perform comparing analysis about the results with two approaches
  - Differences appears in the analyzing aspects of requirement elements and analysis results
    - Results(related PHL) aspects
    - Analysis aspects of each elements in requirements
    - Especially, differences about applying methods are presented about guide phrases
  - Usability of NUREG/CR-6430 about applying FPGA SW is also checked



# **Differences of Analysis aspects**

- Differences of analysis aspects
  - Analysis aspects of requirements points is different with each approaches
  - Comparing results are appeared 'cause' or 'analysis of deviation'

<b>Requirements Point</b>	Analysis Aspects					
	NUREG/CR-6430	HAZOP (GW)				
Sensor	Analysis of deviation	Cause				
Input/output	Analysis of deviation	Cause				
Timing	Analysis of deviation	Cause Analysis of deviation				
Function	Analysis of deviation	Analysis of deviation				
Circuit	Analysis of deviation	Cause				
Security	Analysis of deviation	-				
Memory	Cause	Cause Analysis of deviation				
Data bus	(Analysis of deviation)	Cause Analysis of deviation				
Network	(Analysis of deviation)	Cause Analysis of deviation				

# **Differences of PHL aspects**

• Diffe	Differences of PHL aspects								
	• We compare connected PHL in the analysis results								
	Potential hazards which are analyzed in SW requirement have some different list								

PHL	NUREG/CR-6430	HAZOP (General GW)						
Operation e	error							
a. Operation error of application	0	0						
b. Memory error/failure	N/A	0						
c. Response time error	0	0						
d. Error diagnosis function failure	0	0						
e. Lack of transmit capacity	N/A	N/A						
f. LED failure	0	0						
g. Disability of network	N/A	N/A						
Operation fa	Operation failure							
a. Operation failure by operator (bypass)	0	0						

• Two approaches has different point of view to analyze about each elements of software requirements spec.

• It is appeared by cause and analysis of deviation

- Differences in comparison of PHL do not means usefulness directly
  - We think it caused by extension of difference about analysis aspects
    - Guide phrases about memory is not contained in NUREG/CR-6430

PHL	NUREG/CR-6430	HAZOP (General GW)
Operation e	error	
a. Operation error of application	0	0
b. Memory error/failure	N/A	0
c. Response time error	0	0
d. Error diagnosis function failure	0	0
e. Lack of transmit capacity	N/A	N/A
f. LED failure	0	0
g. Disability of network	N/A	N/A
Operation fa	ailure	
a. Operation failure by operator (bypass)	0	0

• Two approaches has different point of view to analyze about each elements of software requirements spec.

• It is appeared by cause and analysis of deviation

 Differences in comparison of PHL do not means usefulness directly

	\	· · ·	· · · · · · ·			
	• We think	<b>Requirements Point</b>	Analysis Aspects			
	aspects		NUREG/CR-6430	HAZOP (GW)		
	• Guid	Sensor	Analysis of deviation	Cause		
	DU U	Input/output	Analysis of deviation	Cause		
	PHL	Timing	Analysis of deviation	Cause Analysis of deviatior		
a. Operation	error of applica	Function	Analysis of deviation	Analysis of deviation		
b. Memory e	error/failure	Circuit	Analysis of deviation	Cause		
c. Response	time error	Security	Analysis of deviation	-		
	nosis function f ansmit capacity	Memory	Cause	Cause Analysis of deviation		
f. LED failure g. Disability of network		Data bus	(Analysis of deviation)	Cause Analysis of deviation		
	failure by oper	Network	(Analysis of deviation)	Cause Analysis of deviation		

- Additionally, NUREG/CR-6430 provides guide phrases about security, safety and so on
  - These guide phrases make possible to identify whether requirement spec considers about these contents
    - It also can help to analyze non-functional view accordance with these guide phrases
  - Providing guide phrases also makes easy to apply
    - Because, identifying deviation of guide phrases about req. elements is simple



## Conclusion

### • We perform software hazard analysis of FPGA SW requirement

- Using two approaches
  - HAZOP
  - NUREG/CR-6430 guides

We also perform comparing analysis with these approaches

- Perspective of PHL and analysis aspects
- Identifying the usability of NUREG/CR-6430 guides for hazard analysis of FPGA SW requirements specification
  - Some insufficiency points also exists

• We are now planning to supplement the guide phrases to apply efficiently



# Q&A THANK YOU



# **Guide Phrases**

Quality	Aspect	Phase	Guide Phrases	
Accuracy	Sensor	RADC	Stuck at all zeroes	
		RADC	Stuck at all ones	
		RADC	Stuck elsewhere	
		RADC	Below minimum range	
		RADC	Above maximum range	
		RADC	Within range, but wrong	
		RADC	Physical units are incorrect	
		RADC	Wrong data type or data size	
	Circuit	RADC	Stuck at all zeroes	
		RADC	Stuck at all ones	
		RADC	Stuck elsewhere	
	Operator Input &	RA	Numerical value below acceptable range	
	Output	RA	Numerical value above acceptable range	
		RA	Numerical value within range, but wrong	
		RA	Numerical value has wrong physical units	
		RA	Numerical value has wrong data type or data size	
		RA	Non-numerical value incorrect	
		RADC	Message volume exceeds stated maximum	
	Calculation	RDC	Calculated result is outside acceptable error bounds (too low)	
	Corculation	RDC	Calculated result is outside acceptable error bounds (too high)	
		RDC	Formula or equation is wrong	
		RDC	Physical units are incorrect	
		RDC	Wrong data type or data size	
	Memory	RDC	Stuck at all zeroes or ones	
	wernory	RDC	Stuck elsewhere	
Capacity	Timing	RADC	Input signal fails to arrive	
	nining	RADC	Input signal occurs too soon	
		RADC	Input signal occurs too soon	
		RADC	Input signal occurs unexpectedly	
		RADC	System behavior is not deterministic	
		RADC	Output signal fails to arrive at actuator	
		RADC	Output signal arrives too soon	
		RADC	Output signal arrives too late	
		RADC	Output signal arrives unexpectedly	
		R	Insufficient time allowed for operator action	
Functionality		RA	Function is not carried out as specified (for each mode of operation)	
		RA	Function is not initialized properly before being executed	
		R	Function uses incorrect inputs	
Reliability		RA	Software is less reliable than required	
		RA	Software is more reliable than required	
		RA	Software reliability is not known when the system goes into production use	
		RA	Software does not degrade gracefully when required (crashes instead)	
		RA	Software fault tolerance requirements (if any) are not met	
		RA	Reliability varies among the different modes of operation	
		R	Software fails in-service test	
		R	Software fails	
Safety		RA	Software causes system to move to a hazardous state	
-		RA	Software fails to move system from hazardous to nonhazardous state	
		RA	Software fails to initiate emergency shutdown when required to do so	

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