Software Testing and Analysis
Process, Principles, and Techniques

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Introduction

• Text

• This book provides
  – a coherent view of the state of the art and practice
  – technical and organizational approaches to push the state of practice toward the state of the art

• Part I  Fundamentals of Test and Analysis
• Part II  Basic Techniques
• Part III  Problems and Methods
• Part IV  Process
Part I. Fundamentals of Test and Analysis
Chapter 1.
Software Test and Analysis in a Nutshell
Learning Objectives

• View the “big picture” of software quality in the context of a software development project and organization

• Introduce the range of software verification and validation activities

• Provide a rationale for selecting and combining them within a software development process
Engineering Processes

• All engineering processes have two common activities
  – Construction activities
  – Checking activities

• In software engineering (purpose: construction of high quality software)
  – Construction activities
  – Verification activities

• We are focusing on software verification activities.
Software Verification Activities

• Software verification activities take various forms
  – for non-critical products for mass markets
  – for highly-customized products
  – for critical products

• Software verification is particularly difficult, because
  – Many different quality requirements
  – Evolving structure
  – Inherent non-linearity
  – Uneven distribution of faults

< An example of uneven distribution of software faults >
If an elevator can safely carry a load of 1,000 kg, it can also safely carry any smaller load.

If a procedure can correctly sort a set of 256 elements, it may fail on a set of 255 or 53 elements, as well as on 257 or 1,023.
Variety of Approaches

• **No silver bullet** for software verification

• **Software verification designers should**
  – Choose and schedule a right blend of techniques
    • to reach the required level of quality *(concerned with product)*
    • within cost constraints *(concerned with project)*

  – Design a specific solution of V&V activities which can suit to
    • the problem
    • the requirements
    • the development environment
Basic Questions

• To start understanding how to attack the problem of verifying software

1. When do verification and validation start and end?
2. What techniques should be applied?
3. How can we assess the readiness of a product?
4. How can we ensure the quality of successive releases?
5. How can the development process be improved?
1. When Do Verification and Validation Start and End?

- **Test**
  - A widely used V&V activity
  - Usually known as a last activity in software development process
  - But, not the test activity is “test execution”
  - Test execution is a small part of V&V process

- V&V start as soon as we decide to build a software product, or even before.

- V&V last far beyond the product delivery as long as the software is in use, to cope with evolution and adaptations to new conditions.
Early Start: From Feasibility Study

• Feasibility study of a new project must take into account
  – Required qualities
  – Their impact on the overall cost

• Quality related activities include
  – Risk analysis
  – Measures needed to assess and control quality at each stage of development
  – Assessment of the impact of new features and new quality requirements
  – Contribution of quality control activities to development cost and schedule
Long Lasting: Beyond Maintenance

- Maintenance activities include
  - Analysis of changes and extensions
  - Generation of new test suites for the added functionalities
  - Re-executions of tests to check for non regression of software functionalities after changes and extensions
  - Fault tracking and analysis
2. What Techniques Should Be Applied?

- No single A&T technique can serve all purposes.

- The primary reasons for combining techniques are:
  - **Effectiveness** for different classes of faults
    (analysis instead of testing for race conditions)
  - **Applicability** at different points in a project
    (inspection for early requirements validation)
  - **Differences in purpose**
    (statistical testing to measure reliability)
  - **Tradeoffs** in cost and assurance
    (expensive technique for key properties)
<table>
<thead>
<tr>
<th>Process improvement</th>
<th>test case execution and sw validation</th>
<th>Generation of tests</th>
<th>Verification of specs</th>
<th>Planning &amp; monitoring</th>
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<tr>
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<tr>
<td>analyze faults and improve the process</td>
<td>Collect data on faults</td>
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</tbody>
</table>

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3. How Can We Assess the Readiness of a Product?

- A&T activities aim at revealing faults during development.
  - We cannot reveal or remove all faults.
  - A&T cannot last infinitely.

- We have to know whether products meet the quality requirements or not.
  - We must specify the required level of dependability.
    → Measurement
  - We can determine when that level has been attained.
    → Assessment
4. How Can We Ensure the Quality of Successive Releases?

- A&T activities do not stop at the first release.

- Software products operate for many years, and undergo many changes.
  - To adapt to environment changes
  - To serve new and changing user requirements

- Quality tasks after delivery include
  - Test and analysis of new and modified code
  - Re-execution of system tests
  - Extensive record-keeping
5. How Can the Development Process be Improved?

- The same defects are encountered in project after project.
- We can improve the quality through identifying and removing weaknesses
  - in development process
  - in A&T process (quality process)

- 4 steps for process improvement
  1. Define the data to be collected and implementing procedures for collecting them
  2. Analyze collected data to identify important fault classes
  3. Analyze selected fault classes to identify weaknesses in development and quality measures
  4. Adjust the quality and development process
Summary

• The quality process has three different goals
  – Improving a software product
  – Assessing the quality of the software product
  – Improving the quality process

• We need to combine several A&T techniques through the software process.

• A&T depends on organization and application domain.
Chapter 2.
A Framework for Testing and Analysis
Learning Objectives

- Introduce dimensions and tradeoff between test and analysis activities
- Distinguish validation from verification activities
- Understand limitations and possibilities of test and analysis activities
Verification and Validation

- **Validation**: “Does the software system meets the user's real needs?”
  - Are we building the right software?

- **Verification**: “Does the software system meets the requirements specifications?”
  - Are we building the software right?
V&V Depends on the Specification

- **Unverifiable (but validatable) specification:** “If a user presses a request button at floor \( i \), an available elevator must arrive at floor \( i \) **soon.**”

- **Verifiable specification:** “If a user presses a request button at floor \( i \), an available elevator must arrive at floor \( i \) **within 30 seconds**”
V-Model of V&V Activities
Undeciability of Correctness Properties

- Correctness properties are not decidable.
  - Halting problem can be embedded in almost every property of interest.
Verification Trade-off Dimensions

- **Optimistic inaccuracy**
  - We may accept some programs that do not possess the property.
  - It may not detect all violations.
  - Example: Testing

- **Pessimistic inaccuracy**
  - It is not guaranteed to accept a program even if the program does possess the property being analyzed, because of false alarms.
  - Example: Automated program analysis

- **Simplified properties**
  - It reduces the degree of freedom by simplifying the property to check.
  - Example: Model Checking
Terms related to Pessimistic and Optimistic

**Safe:**
A safe analysis has no optimistic inaccuracy; that is, it accepts only correct programs.

**Sound:**
An analysis of a program $P$ with respect to a formula $F$ is sound, if the analysis returns True only when the program actually does satisfy the formula.

**Complete:**
An analysis of a program $P$ with respect to a formula $F$ is complete, if the analysis always returns true when the program actually does satisfy the formula.
Summary

• Most interesting properties are undecidable, thus in general we cannot count on tools that work without human intervention.

• Assessing program qualities comprises two complementary sets of activities:
  – Validation (Does the software do what it is supposed to do?)
  – Verification (Does the system behave as specified?)

• There is no single technique for all purposes.
  – V&V designers need to select a suitable combination of techniques.
Chapter 3.
Basic Principles
Learning Objectives

• Understand the basic principles underlying A&T techniques.

• Grasp the motivations and applicability of the main principles.
Main A&T Principles

- Principles for general engineering:
  - Partition: divide and conquer
  - Visibility: making information accessible
  - Feedback: tuning the development process

- Principles specific to software A&T:
  - Sensitivity: better to fail every time than sometimes
  - Redundancy: making intentions explicit
  - Restriction: making the problem easier
1. Sensitivity

- “It is better to fail every time than sometimes.”
- Consistency

- A test selection criterion works better if every selected test provides the same result.
  - i.e. if the program fails with one of the selected tests, then it fails with all of them. (reliable criteria)

- Run time deadlock analysis works better if it is machine independent.
  - i.e. if the program deadlocks when analyzed on one machine, then it deadlocks on every machine.
2. Redundancy

• “Make intention explicit.”

• Redundant checks can increase the capabilities of catching specific faults early or more efficiently.
  – Static type checking is redundant with respect to dynamic type checking, but it can reveal many type mismatches earlier and more efficiently.
  – Validation of requirement specifications is redundant with respect to validation of the final software, but can reveal errors earlier and more efficiently.
  – Testing and proof of properties are redundant, but are often used together to increase confidence.
3. Restriction

• “Make the problem easier.”

• Suitable restrictions can reduce hard (unsolvable) problems to simpler (solvable) problems.

• A weaker spec may be easier to check:
  – It is impossible (in general) to show that pointers are used correctly, but the simple Java requirement that pointers are initialized before use is simple to enforce.

• A stronger spec may be easier to check:
  – It is impossible (in general) to show that type errors do not occur at run-time in a dynamically typed language, but statically typed languages impose stronger restrictions that are easily checkable.
4. Partition

• “Divide and conquer.”

• Hard testing and verification problems can be handled by suitably partitioning the input space.
  – Both structural and functional test selection criteria identify suitable partitions of code or specifications.
  – Verification techniques fold the input space according to specific characteristics, grouping homogeneous data together and determining partitions.
5. Visibility

- “Make information accessible.”

- The ability to measure progress or status against goals
  - $X$ visibility = ability to judge how we are doing on $X$
  - schedule visibility = “Are we ahead or behind schedule?”
  - quality visibility = “Does quality meet our objectives?”

- Involves setting goals that can be assessed at each stage of development.

- The biggest challenge is early assessment
  e.g., assessing specifications and design with respect to product quality
6. Feedback

• “Tune the development process.”

• Learning from experience:
  – Each project provides information to improve the next.

• Examples
  – Checklists are built on the basis of errors revealed in the past.
  – Error taxonomies can help in building better test selection criteria.
  – Design guidelines can avoid common pitfalls.
Summary

- The discipline of A&T is characterized by 6 main principles:
  - Sensitivity: better to fail every time than sometimes
  - Redundancy: making intentions explicit
  - Restriction: making the problem easier
  - Partition: divide and conquer
  - Visibility: making information accessible
  - Feedback: tuning the development process

- They can be used to understand advantages and limits of different approaches and compare different techniques.
Chapter 4.
Test and Analysis Activities within a Software Process
Learning Objectives

- Understand the role of quality in the development process
- Build an overall picture of the quality process
- Identify the main characteristics of a quality process
  - Visibility
  - Anticipation of activities
  - Feedback
Software Quality and Process

• Qualities cannot be added after development
  – Quality results from a set of inter-dependent activities.
  – Analysis and testing are crucial but far from sufficient.

• Testing is not a phase, but a lifestyle
  – Testing and analysis activities occur from early in requirements engineering through delivery and subsequent evolution.
  – Quality depends on every part of the software process.

• An essential feature of software processes is that software test and analysis is thoroughly integrated and not an afterthought
Quality Process

• Quality process
  – A set of activities and responsibilities
    • Focused on ensuring adequate dependability
    • Concerned with project schedule or with product usability

• Quality process provides a framework for
  – Selecting and arranging A&T activities
  – Considering interactions and trade-offs with other important goals
An Example of Other Important Goals

- "High dependability" vs. "Time to market"

- Mass market products:
  - Better to achieve a reasonably high degree of dependability on a tight schedule than to achieve ultra-high dependability on a much longer schedule

- Critical medical devices:
  - Better to achieve ultra-high dependability on a much longer schedule than a reasonably high degree of dependability on a tight schedule
Planning and Monitoring

• Quality process
  – A&T planning
  – Balances several activities across the whole development process
  – Selects and arranges them to be as cost-effective as possible
  – Improves early visibility

• A&T planning is integral to the quality process.
  – Quality goals can be achieved only through careful planning.
Process Visibility

• A process is visible to the extent that one can answer the question:
  – How does our progress compare to our plan?
  – Example: Are we on schedule? How far ahead or behind?

• The quality process can achieve adequate visibility, if one can gain strong confidence in the quality of the software system, before it reaches final testing
  – Quality activities are usually placed as early as possible
    • Design test cases at the earliest opportunity
    • Uses analysis techniques on software artifacts produced before actual code
  – Motivates the use of “proxy” measures
    • Example: the number of faults in design or code is not a true measure of reliability, but we may count faults discovered in design inspections as an early indicator of potential quality problems.
A&T Plan

- A comprehensive description of the quality process that includes:
  - objectives and scope of A&T activities
  - documents and other items that must be available
  - items to be tested
  - features to be tested and not to be tested
  - analysis and test activities
  - staff involved in A&T
  - constraints
  - pass and fail criteria
  - schedule
  - deliverables
  - hardware and software requirements
  - risks and contingencies
Quality Goals

• Goal must be further refined into a clear and reasonable set of objectives.

• Product quality: goals of software quality engineering
• Process quality: means to achieve the goals

• Product qualities
  – Internal qualities: invisible to clients
    • maintainability, flexibility, reparability, changeability
  – External qualities: directly visible to clients
    • Usefulness:
      – usability, performance, security, portability, interoperability
    • Dependability:
      – correctness, reliability, safety, robustness
Dependability Properties

• Correctness
  – A program is correct if it is consistent with its specification.
  – Seldom practical for non-trivial systems

• Reliability
  – Likelihood of correct function for some “unit” of behavior
  – Statistical approximation to correctness (100% reliable = correct)

• Safety
  – Concerned with preventing certain undesirable behavior, called hazards

• Robustness
  – Providing acceptable (degraded) behavior under extreme conditions
  – Fail softly
An Example of Dependability Property

- **Correctness, Reliability:**
  - Let traffic pass according to correct pattern and central scheduling

- **Robustness, Safety:**
  - Provide degraded function when it fails
  - Never signal conflicting greens
    - Blinking red / blinking yellow is better than no lights.
    - No lights is better than conflicting greens.
Relationship among Dependability Properties

- **Robust but not Safe:** Catastrophic failures can occur.
- **Reliable but not Correct:** Failures can occur rarely.
- **Correct but not Safe nor Robust:** The specification is inadequate.
- **Safe but not Correct:** Annoying failures can occur.
Analysis

• Do not involve actual execution of program source code
  – Manual inspection
  – Automated static analysis

• Inspection technique
  – Can be applied to essentially any document
  – Takes a considerable amount of time
  – Re-inspecting a changed component can be expensive.

• Automatic static analysis
  – Can be applied to some formal representations of requirements models
  – Not to natural language documents
  – Substituting machine cycles for human effort makes them particularly cost-effective.
Testing

- Executed late in development, but
- Start as early as possible

- Early test generation has several advantages:
  - Tests are generated independently from code, when the specifications are fresh in the mind of analysts.
  - Generation of test cases may highlight inconsistencies and incompleteness of the corresponding specifications.
  - Tests may be used as compendium of the specifications by the programmers.
Improving the Process

- Long lasting errors are common.
- It is important to structure the process for
  - Identifying the most critical persistent faults
  - Tracking them to frequent errors
  - Adjusting the development and quality processes to eliminate errors

- Feedback mechanisms are the main ingredient of the quality process for identifying and removing errors.
Organizational Factors

• Different teams for development and quality?
  – Separate development and quality teams is common in large organizations.

• Different roles for development and quality?
  – Test designer is a specific role in many organizations
  – Mobility of people and roles by rotating engineers over development and testing tasks among different projects is a possible option.
An Example of Allocation of Responsibility

- Allocating tasks and responsibilities is a complex job

- Unit testing
  - to the development team (requires detailed knowledge of the code)
  - but the quality team may control the results (structural coverage)

- Integration, system and acceptance testing
  - to the quality team
  - but the development team may produce scaffolding and oracles

- Inspection and walk-through
  - to mixed teams

- Regression testing
  - to quality and maintenance teams

- Process improvement related activities
  - to external specialists interacting with all teams
Summary

• A&Ts are complex activities that must be suitably planned and monitored.

• A good quality process obeys some basic principles:
  – Visibility
  – Early activities
  – Feedback

• Aims at
  – Reducing occurrences of faults
  – Assessing the product dependability before delivery
  – Improving the process
Part II. Basic Techniques
Chapter 5.
Finite Models
Learning Objectives

• Understand goals and implications of finite state abstraction

• Learn how to model program control flow with graphs

• Learn how to model the software system structure with call graphs

• Learn how to model finite state behavior with finite state machines
Model

- A model is
  - A representation that is simpler than the artifact it represents,
  - But preserves some important attributes of the actual artifact

- Our concern is with models of program execution.
Directed Graph

- Directed graph:
  - N: set of nodes
  - E: set of edges (relation on the set of nodes)

\[ N = \{ a, b, c \} \]
\[ E = \{ (a, b), (a, c), (c, a) \} \]
Directed Graph with Labels

- We can label nodes with the names or descriptions of the entities they represent.
  - If nodes $a$ and $b$ represent program regions containing assignment statements, we might draw the two nodes and an edge $(a, b)$ connecting them in this way:

\[
x = y + z; \\
a = f(x);
\]
Finite Abstractions of Behavior

- Two effects of abstraction
  1. Coarsening of execution model
  2. Introduction of nondeterminism
Intraprocedural Control Flow Graph

• Called “Control Flow Graph” or “CGF”
  – A directed graph \((N, E)\)

• Nodes
  – Regions of source code (basic blocks)
  – Basic block = maximal program region with a single entry and single exit point
  – Statements are often grouped in single regions to get a compact model.
  – Sometime single statements are broken into more than one node to model control flow within the statement.

• Directed edges
  – Possibility that program execution proceeds from the end of one region directly to the beginning of another
public static String collapseNewlines(String argStr) {
    char last = argStr.charAt(0);
    StringBuffer argBuf = new StringBuffer();
    for (int cIdx = 0; cIdx < argStr.length(); cIdx++) {
        char ch = argStr.charAt(cIdx);
        if (ch != '
' || last != '
') {
            argBuf.append(ch);
            last = ch;
        }
    }
    return argBuf.toString();
}
The Use of CFG

- CFG may be used directly to define thoroughness criteria for testing.
  - Chapter 9. Test Case Selection and Adequacy
  - Chapter 12. Structural Testing

- Often, CFG is used to define another model which is used to define a thoroughness criterion
  - Example: LCSAJ is derived from the CGF
    - Essential sub-paths of the CFG from one branch to another
LCSAJ (Linear Code Sequence And Jump)

```
public static String collapseNewlines(String argStr)
{
    char last = argStr.charAt(0);
    StringBuffer argBuf = new StringBuffer();
    for (int clidx = 0; clidx < argStr.length();)
    {
        char ch = argStr.charAt(clidx);
        if (ch != '
')
        {
            if (last != ch)
            {
                argBuf.append(ch);
                last = ch;
            }
            clidx++;
        }
    }
    return argBuf.toString();
}
```

<table>
<thead>
<tr>
<th>From</th>
<th>Sequence of Basic Blocks</th>
<th>To</th>
</tr>
</thead>
<tbody>
<tr>
<td>entry</td>
<td>b1 b2 b3</td>
<td>jX</td>
</tr>
<tr>
<td>entry</td>
<td>b1 b2 b3 b4</td>
<td>jT</td>
</tr>
<tr>
<td>entry</td>
<td>b1 b2 b3 b4 b5</td>
<td>jE</td>
</tr>
<tr>
<td>entry</td>
<td>b1 b2 b3 b4 b5 b6 b7</td>
<td>jL</td>
</tr>
<tr>
<td>bX</td>
<td></td>
<td>jX</td>
</tr>
<tr>
<td>b4</td>
<td></td>
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</tr>
<tr>
<td>bL</td>
<td>b3 b4 b5 b6 b7</td>
<td>jL</td>
</tr>
</tbody>
</table>
Call Graphs

- “Interprocedural Control Flow Graph”
  - A directed graph (N, E)

- Nodes
  - Represent procedures, methods, functions, etc.

- Edges
  - Represent ‘call’ relation

- Call graph presents many more design issues and trade-off than CFG.
  - Overestimation of call relation
  - Context sensitive/insensitive
Overestimation in a Call Graph

- The static call graph includes calls through dynamic bindings that never occur in execution.

```java
class C {
    public static C cFactory(String kind) {
        if (kind == "C") return new C();
        if (kind == "S") return new S();
        return null;
    }
    void foo() {
        System.out.println("You called the parent's method");
    }
    public static void main(String args[]) {
        (new A()).check();
    }
}
class S extends C {
    void foo() {
        System.out.println("You called the child's method");
    }
}
class A {
    void check() {
        C myC = C.cFactory("S");
        myC.foo();
    }
}
```
public class Context {
    public class Context {
        public static void main(String args[]) {
            Context c = new Context();
            c.foo(3);
            c.bar(17);
        }

        void foo(int n) {
            int[] myArray = new int[n];
            depends(myArray, 2);
        }

        void bar(int n) {
            int[] myArray = new int[n];
            depends(myArray, 16);
        }

        void depends(int[] a, int n) {
            a[n] = 42;
        }
    }
}

< Context Insensitive >

< Context Sensitive >
Calling Paths in Context Sensitive Call Graphs

1 context A

2 contexts AB AC

4 contexts ABD ABE ACD ACE

8 contexts ...

16 calling contexts ... exponentially grow.
Finite State Machines

- CFGs can be extracted from programs.
- FSMs are constructed prior to source code, and serve as specifications.
  - A directed graph \((N, E)\)
  - CFG and FSM are duals.

- Nodes
  - A finite set of states
- Edges
  - A set of transitions among states

<table>
<thead>
<tr>
<th></th>
<th>LF</th>
<th>CR</th>
<th>EOF</th>
<th>other char</th>
</tr>
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<tbody>
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</table>
Correctness Relations for FSM Models

The model satisfies The specification
The model is syntactically well-formed, consistent and complete
The model accurately represents the program

```java
public static Table1 getTable1()
    { 
    if (ref == null) {
        synchronised(Table1) {
            if (ref == null){
                ref = new Table1();
                ref.initialize();
            }  
        }
    } 
    return ref; 
} ...
```
Abstract Function for Modeling FSMs

```c
/* Convert each line from standard input */
void transduce() {

#define BUFLEN 1000
char buf[BUFLEN]; /* Accumulate line into this buffer */
int pos = 0; /* Index for next character in buffer */

char inChar; /* Next character from input */
int atCR = 0; /* 0=“within line”, 1=“optional DOS LF” */

while ((inChar = getchar()) != EOF) {
    switch (inChar) {
    case LF:
        if (atCR) { /* Optional DOS LF */
            atCR = 0;
        } else { /* Encountered CR within line */
            emit(buf, pos);
            pos = 0;
        }
    break;
    case CR:
        emit(buf, pos);
        pos = 0;
        atCR = 1;
    break;
    default:
        if (pos >= BUFLEN-2) fail("Buffer overflow");
        buf[pos++] = inChar;
    }
    /* switch */
}
if (pos > 0) {
    emit(buf, pos);
}
}
```

<table>
<thead>
<tr>
<th>Abstract state</th>
<th>Concrete state</th>
</tr>
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<tbody>
<tr>
<td>e (Empty buffer)</td>
<td>Lines 3 – 13</td>
</tr>
<tr>
<td>w (Within line)</td>
<td>13</td>
</tr>
<tr>
<td>l (Looking for LF)</td>
<td>13</td>
</tr>
<tr>
<td>d (Done)</td>
<td>36</td>
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</tbody>
</table>

Modeling with abstraction

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</tbody>
</table>
Summary

- Models must be much simpler than the artifact they describe in order to be understandable and analyzable.
- Models must be sufficiently detailed to be useful.
- CFG are built from software program.
- FSM can be built before software program to document behavior.
Chapter 6.
Data Dependency and Data Flow Models
Learning Objectives

• Understand basics of data-flow models and the related concepts (def-use pairs, dominators...)

• Understand some analyses that can be performed with the data-flow model of a program
  – Data flow analyses to build models
  – Analyses that use the data flow models

• Understand basic trade-offs in modeling data flow
Why Data Flow Models Need?

• Models from Chapter 5 emphasized control flow only.
  – Control flow graph, call graph, finite state machine

• We also need to reason about data dependence.
  – To reason about transmission of information through program variables
  – “Where does this value of x come from?”
  – “What would be affected by changing this? “
  – ...

• Many program analyses and test design techniques use data flow information and dependences
  – Often in combination with control flow
Definition-Use Pairs

• A def-use (du) pair associates a point in a program where a value is produced with a point where it is used

• Definition: where a variable gets a value
  – Variable declaration
  – Variable initialization
  – Assignment
  – Values received by a parameter

• Use: extraction of a value from a variable
  – Expressions
  – Conditional statements
  – Parameter passing
  – Returns
Def-Use Pairs

... if (...) {
    x = ... ;
    ...
} y = ... + x + ... ;
...

if (...) {
    x = ...

    x = ...
    ...

    y = ... + x + ...
    ...
}

Definition: x gets a value
Use: the value of x is extracted

Def-Use path
/** Euclid's algorithm */

public int gcd(int x, int y) {
    int tmp;                // A: def x, y, tmp
    while (y != 0) {     // B: use y
        tmp = x % y; // C: def tmp; use x, y
        x = y;       // D: def x; use y
        y = tmp;     // E: def y; use tmp
    }
    return x;        // F: use x
}
Definition-Clear & Killing

• A definition-clear path is a path along the CFG from a definition to a use of the same variable without another definition of the variable between.

• If, instead, another definition is present on the path, then the latter definition kills the former

• A def-use pair is formed if and only if there is a definition-clear path between the definition and the use
Definition-Clear & Killing

\[ x = \ldots \quad \text{// A: def x} \]
\[ q = \ldots \]
\[ x = y; \quad \text{// B: kill x, def x} \]
\[ z = \ldots \]
\[ y = f(x); \quad \text{// C: use x} \]

Path A..C is not definition-clear

Path B..C is definition-clear

Definition: \( x \) gets a value

Definition: \( x \) gets a new value, old value is killed

Use: the value of \( x \) is extracted
(Direct) Data Dependence Graph

- Direct data dependence graph
  - A direct graph \((N, E)\)
  - Nodes: as in the control flow graph (CFG)
  - Edges: def-use (du) pairs, labelled with the variable name

```java
/** Euclid's algorithm */
public int gcd(int x, int y) {
    int tmp; // A: def x, y, tmp
    while (y != 0) { // B: use y
        tmp = x % y; // C: def tmp; use x, y
        x = y; // D: def x; use y
        y = tmp; // E: def y; use tmp
    }
    return x; // F: use x
}
```
Control Dependence

- Data dependence
  - “Where did these values come from?”

- Control dependence
  - “Which statement controls whether this statement executes?”
  - A directed graph
    - Nodes: as in the CFG
    - Edges: unlabelled, from entry/branching points to controlled blocks

```java
/** Euclid's algorithm */
public int gcd(int x, int y) {
    int tmp; // A: def x, y, tmp
    while (y != 0) { // B: use y
        tmp = x % y; // C: def tmp; use x, y
        x = y; // D: def x; use y
        y = tmp; // E: def y; use tmp
    }
    return x; // F: use x
}
```
Dominator

- **Pre-dominators** in a rooted, directed graph can be used to make this intuitive notion of “controlling decision” precise.

- Node M **dominates** node N, if every path from the root to N passes through M.
  - A node will typically have many dominators, but except for the root, there is a unique immediate dominator of node N which is closest to N on any path from the root, and which is in turn dominated by all the other dominators of N.
  - Because each node (except the root) has a unique immediate dominator, the immediate dominator relation forms a tree.

- **Post-dominators** are calculated in the reverse of the control flow graph, using a special “exit” node as the root.
An Example of Dominators

- A pre-dominates all nodes.
- G post-dominates all nodes.

- F and G post-dominate E.
- G is the immediate post-dominator of B.

- C does not post-dominate B.

- B is the immediate pre-dominator of G.
- F does not pre-dominate G.
More Precise Definition of Control Dependence

• We can use post-dominators to give a more precise definition of control dependence
  – Consider again a node $N$ that is reached on some but not all execution paths.
  – There must be some node $C$ with the following property:
    • $C$ has at least two successors in the control flow graph (i.e., it represents a control flow decision).
    • $C$ is not post-dominated by $N$.
    • There is a successor of $C$ in the control flow graph that is post-dominated by $N$.
  – When these conditions are true, we say node $N$ is control-dependent on node $C$.

• Intuitively, $C$ is the last decision that controls whether $N$ executes.
An Example of Control Dependence

- **Execution of F is not inevitable at B**
- **Execution of F is inevitable at E**
- **F is control-dependent on B, the last point at which its execution was not inevitable**
Data Flow Analysis

• Describes the algorithms used to compute data flow information.
  – Basic algorithms used widely in compilers, test and analysis tools, and other software tools.

• Too difficult → Skipped.
Summary

• Data flow models detect patterns on CFGs.
  – Nodes initiating the pattern
  – Nodes terminating it
  – Nodes that may interrupt it

• Data dependence information
  – Pros:
    • Can be implemented by efficient iterative algorithms
    • Widely applicable (not just for classic “data flow” properties)
  – Limitations:
    • Unable to distinguish feasible from infeasible paths
    • Analyses spanning whole programs (e.g., alias analysis) must trade off precision against computational cost
Chapter 7.
Symbolic Execution and Proof of Properties
Learning Objectives

• Understand the goal and implication of symbolically executing programs

• Learn how to use assertions to summarize infinite executions
• Learn how to reason about program correctness
• Learn how to use symbolic execution to reason about program properties

• Understand limits and problems of symbolic execution
Symbolic Execution

• Builds predicates that characterize
  – Conditions for executing paths
  – Effects of the execution on program state

• Bridges program behavior to logic

• Finds important applications in
  – Program analysis
  – Test data generation
  – Formal verification (proofs) of program correctness
    • Rigorous proofs of properties of critical subsystems
      – Example: safety kernel of a medical device
    • Formal verification of critical properties particularly resistant to dynamic testing
      – Example: security properties
    • Formal verification of algorithm descriptions and logical designs
      – less complex than implementations
Symbolic State and Interpretation

- Tracing execution with symbolic values and expressions is the basis of symbolic execution.
  - Values are expressions over symbols.
  - Executing statements computes new expressions with the symbols.

**Execution with concrete values**

(before)
low 12
high 15
mid -

mid = (high + low) / 2

(after)
low 12
high 15
mid 13

**Execution with symbolic values**

(before)
low L
high H
mid -

mid = (high + low) / 2

(after)
Low L
high H
mid (L+H) / 2
Tracing Execution with Symbolic Executions

char *binarySearch( char *key, char *dictKeys[], char *dictValues[], int dictSize) {
    int low = 0;
    int high = dictSize - 1;
    int mid;
    int comparison;

    while (high >= low) {
        mid = (high + low) / 2;
        comparison = strcmp(dictKeys[mid], key);
        if (comparison < 0) {
            low = mid + 1;
        } else if (comparison > 0) {
            high = mid - 1;
        } else {
            return dictValues[mid];
        }
    }
    return 0;
}

∀ k, 0 ≤ k < size : dictKeys[k] = key → L ≤ k ≤ H
∀ H ≥ M ≥ L
Summary Information

- Symbolic representation of paths may become extremely complex.

- We can simplify the representation by replacing a complex condition $P$ with a weaker condition $W$ such that
  
  \[ P \Rightarrow W \]

  - $W$ describes the path with less precision
  - $W$ is a \textit{summary} of $P$
An Example of Summary Information

- If we are reasoning about the correctness of the binary search algorithm,
  - In “mid = (high+low)/2”

  Complete condition:
  
  \[ \begin{align*}
  low &= L \\
  \land high &= H \\
  \land mid &= M \\
  \land M &= (L+H) / 2
  \end{align*} \]

  Weaker condition:
  
  \[ \begin{align*}
  low &= L \\
  \land high &= H \\
  \land mid &= M \\
  \land L \leq M \leq H
  \end{align*} \]

- The weaker condition contains less information, but still enough to reason about correctness.
Weaker Precondition

• The weaker predicate $L \leq mid \leq H$ is chosen based on what must be true for the program to execute correctly.
  – It cannot be derived automatically from source code.
  – It depends on our understanding of the code and our rationale for believing it to be correct.

• A predicate stating what *should* be true at a given point can be expressed in the form of an assertion

• Weakening the predicate has a cost for testing
  – Satisfying the predicate is no longer sufficient to find data that forces program execution along that path.
    • Test data satisfying a weaker predicate $W$ is necessary to execute the path, but it may not be sufficient.
    • Showing that $W$ cannot be satisfied shows path infeasibility.
Loops and Assertions

- The number of execution paths through a program with loops is potentially infinite.
- To reason about program behavior in a loop, we can place within the loop an **invariant**.
  - Assertion that states a predicate that is expected to be true each time execution reaches that point

- Each time program execution reaches the invariant assertion, we can weaken the description of program state.
  - If predicate P represents the program state and the assertion is W
  - We must first ascertain P => W
  - And then we can substitute W for P
Precondition and Postcondition

- Supposed that
  - Every loop contains an assertion
  - There is an assertion at the beginning of the program
  - There is a final assertion at the end

- Then
  - Every possible execution path would be a sequence of segments from one assertion to the next.

- Precondition: the assertion at the beginning of a segment
- Postcondition: the assertion at the end of the segment
Verification of Program Correctness

- For each program segment, if we can verify that
  - Starting from the precondition,
  - Executing the program segment,
  - And postcondition holds at the end of the segment

- Then, we verify the correctness of an infinite number of program paths.
An Example of Verification with Assertions

```c
char *binarySearch( char *key, char *dictKeys[ ],
   char *dictValues[ ], int dictSize) {

   int low = 0;
   int high = dictSize - 1;
   int mid;
   int comparison;

   while (high >= low) {
      mid = (high + low) / 2;
      comparison = strcmp( dictKeys[mid], key );
      if (comparison < 0) {
         low = mid + 1;
      } else if ( comparison > 0 ) {
         high = mid - 1;
      } else {
         return dictValues[mid];
      }
   }
   return 0;
}
```

**Precondition:** “should be sorted”
\[ \forall i, j, 0 \leq i < j < \text{size} : \text{dictKeys}[i] \leq \text{dictKeys}[j] \]

**Invariant:** “should be in range”
\[ \forall i, 0 \leq i < \text{size} : \text{dictKeys}[i] = \text{key} \rightarrow \text{low} \leq i \leq \text{high} \]
When Executing the Loop

Initial values:

\[
\begin{align*}
& \text{low} = L \\
& \land \text{high} = H
\end{align*}
\]

Instantiated invariant:

\[
\begin{align*}
& \forall i, j, 0 \leq i < j < \text{size} : \text{dictKeys}[i] \leq \text{dictKeys}[j] \\
& \land \forall k, 0 \leq k < \text{size} : \text{dictKeys}[k] = \text{key} \rightarrow L \leq k \leq H
\end{align*}
\]

After executing:

\[
\text{mid} = (\text{high} + \text{low}) / 2
\]

\[
\begin{align*}
& \text{low} = L \\
& \land \text{high} = H \\
& \land \text{mid} = M \\
& \land \forall i, j, 0 \leq i < j < \text{size} : \text{dictKeys}[i] \leq \text{dictKeys}[j] \\
& \land \forall k, 0 \leq k < \text{size} : \text{dictKeys}[k] = \text{key} \rightarrow L \leq k \leq H \\
& \land H \geq M \geq L
\end{align*}
\]
After executing the Loop

After executing the loop:

\[
\begin{align*}
\text{low} &= \text{M+1} \\
\wedge \text{high} &= \text{H} \\
\wedge \text{mid} &= \text{M} \\
\wedge \forall i, j, 0 \leq i < j < \text{size} : \text{dictKeys}[i] &\leq \text{dictKeys}[j] \\
\wedge \forall k, 0 \leq k < \text{size} : \text{dictKeys}[k] = \text{key} \rightarrow \text{L} \leq k \leq \text{H} \\
\wedge \text{H} &\geq \text{M} \geq \text{L} \\
\wedge \text{dictkeys}[\text{M}] &< \text{key}
\end{align*}
\]

The new instance of the invariant:

\[
\begin{align*}
\forall i, j, 0 \leq i < j < \text{size} : \text{dictKeys}[i] &\leq \text{dictKeys}[j] \\
\wedge \forall k, 0 \leq k < \text{size} : \text{dictKeys}[k] = \text{key} \rightarrow \text{M+1} \leq k \leq \text{H}
\end{align*}
\]

→ If the invariant is satisfied,
the loop is correct with respect to the preconditions and the invariant.
At the End of the Loop

Even the invariant is satisfied, but the postcondition is false:

\[
\begin{align*}
\text{low} &= L \\
\land \quad \text{high} &= H \\
\land \quad \forall i, j, 0 \leq i < j < \text{size} : \text{dictKeys}[i] \leq \text{dictKeys}[j] \\
\land \quad \forall k, 0 \leq k < \text{size} : \text{dictKeys}[k] = \text{key} \to L \leq k \leq H \\
\land \quad L > H 
\end{align*}
\]

If the condition satisfies the post-condition, the program is correct with respect to the pre- and post-condition.
Compositional Reasoning

• Follow the hierarchical structure of a program
  – at a small scale (within a single procedure)
  – at larger scales (across multiple procedures)

• Hoare triple: \([\text{pre}] \text{ block } [\text{post}]\)

• If the program is in a state satisfying the precondition \(\text{pre}\) at entry to the block, then after execution of the block, it will be in a state satisfying the postcondition \(\text{post}\)
Reasoning about Hoare Triples: Inference

**While loops:**

<table>
<thead>
<tr>
<th>Premise</th>
<th>Conclusion</th>
</tr>
</thead>
<tbody>
<tr>
<td>([ I \land C ] S [ I ])</td>
<td>([ I ] \text{ while}(C) { S } [I \land \neg C])</td>
</tr>
</tbody>
</table>

Inference rule says:
if we can verify the premise (top),
then we can infer the conclusion (bottom)
Other Inference Rule

if statement:

\[
\begin{align*}
&[P \land C] \text{ thenpart } [Q] & [P \land \neg C] \text{ elsepart } [Q] \\
&[P] \text{ if } (C) \{\text{thenpart}\} \text{ else } \{\text{elsepart}\} [Q]
\end{align*}
\]
Reasoning Style

• Summarize the effect of a block of program code (a whole procedure) by a "contract == precondition + postcondition"
• Then use the contract wherever the procedure is called

• Summarizing binarySearch:

\[(\forall i, j, 0 \leq i < j < \text{size} : \text{keys}[i] \leq \text{keys}[j]) \text{ <-- precondition}\]

\[s = \text{binarySearch}(k, \text{keys}, \text{vals}, \text{size})\]

\[(s = v \text{ and } \exists i, 0 \leq i, \text{size} : \text{keys}[i] = k \land \text{vals}[i] = v) \text{ <-- postcondition}\]
\[\lor (s = v \land \neg \exists i, 0 \leq i, \text{size} : \text{keys}[i] = k)\]
Reasoning about Data Structures and Classes

• Data structure module
  = Collection of procedures (methods) whose specifications are strongly interrelated

• Contracts: specified by relating procedures to an abstract model of their (encapsulated) inner state

• Example:
  – Dictionary can be abstracted as {<key, value>}
  – Implemented independently as a list, tree, hash table, etc.
Structural Invariant & Abstract Function

• **Structural invariants** are the structural characteristics that must be maintained. (directly analogous to loop invariants)
  – Example: Each method in a search tree class should maintain the ordering of keys in the tree.

• **Abstract function** maps concrete objects to abstract model states.
  – Example: Dictionary
    • \[ <k,v> \in \Phi(\text{dict}) \]
    • \( o = \text{dict.get}(k) \)
    • \[ o = v \]
Summary

• Symbolic execution is a bridge from an operational view of program execution to logical and mathematical statements.
• Basic symbolic execution technique is the execution using symbols.

• Symbolic execution for loops, procedure calls, and data structures: proceed hierarchically
  – compose facts about small parts into facts about larger parts

• Fundamental technique for
  – Generating test data
  – Verifying systems
  – Performing or checking program transformations

• Tools are essential to scale up.
Chapter 8.
Finite State Verification
Learning Objectives

- Understand the purpose and appropriate uses of finite-state verification
  - Understand how FSV mitigates weaknesses of testing
  - Understand how testing complements FSV

- Understand modeling for FSV as a balance between cost and precision

- Distinguish explicit state enumeration from analysis of implicit models
  - Understand why implicit models are sometimes (but not always) more effective
Overview

• Most important properties of program execution are not decidable.
• Finite state verification can automatically prove some significant properties of a finite model of the infinite execution space.

• Need to balance trade-offs among
  – Generality of properties to be checked
  – Class of programs or models that can be checked
  – Computational effort in checking
  – Human effort in producing models and specifying properties
Resources and Results

Properties to be proved:
- complex
- simple

Computational cost:
- low
- high

Finite state verification applies techniques from symbolic execution and formal verification to models that abstract the potentially infinite state space of program behavior into finite representations.

Control and data flow models apply low computational cost.
Cost of FSV

- Human effort and skill are required.
  - to prepare a finite state model
  - to prepare a suitable specification for automated analysis

- Iterative process of FSV
  1. Prepare a model and specify properties
  2. Attempt verification
  3. Receive reports of impossible or unimportant faults
  4. Refine the specification or the model
Finite State Verification Framework

```java
... public static Table1 getTable1() {
    if (ref == null) {
        synchronized(Table1) {
            if (ref == null) {
                ref = new Table1();
                ref.initialize();
            }
        }
    return ref;
}
...```

- PROGRAM or DESIGN
- Derive models of software or design
- MODEL
  - (a)
  - (b)
  - (c)
  - (d)
  - (e)
  - (f)
- Direct check of source/design (impractical or impossible)
- PROPERTY OF INTEREST
- Implication
- PROPERTY OF THE MODEL
- `never(<d> and <y>)`

No concurrent modifications of Table1
Applications for Finite State Verifications

- Concurrent (multi-threaded, distributed, ...) system
  - Difficult to test thoroughly (apparent non-determinism based on scheduler)
  - Sensitive to differences between development environment and field environment
  - First and most well-developed application of FSV

- Data models
  - Difficult to identify “corner cases” and interactions among constraints, or to thoroughly test them

- Security
  - Some threats depend on unusual (and untested) use
An Example: Modeling Concurrent System

• Deriving a good finite state model is hard.

• Example: FSM model of a program with multiple threads of control
  – Simplifying assumptions
    • We can determine in advance the number of threads.
    • We can obtain a finite state machine model of each thread.
    • We can identify the points at which processes can interact.
  – State of the whole system model
    • Tuple of states of individual process models
  – Transition
    • Transition of one or more of the individual processes, acting individually or in concert
State Space Explosion – An Example

• On-line purchasing system

• Specification
  – In-memory data structure initialized by reading configuration tables at system start-up
  – Initialization of the data structure must appear atomic.
  – The system must be reinitialized on occasion.
  – The structure is kept in memory.

• Implementation (with bugs)
  – No monitor (e.g. Java synchronized), because it’s too expensive.
  – But, use double-checked locking idiom* for a fast system
    *Bad decision, broken idiom ... but extremely hard to find the bug through testing.
On-line Purchasing System - Implementation

class Table1 {
    private static Table1 ref = null;
    private boolean needsInit = true;
    private ElementClass [ ] theValues;
    private Table1() { }

    public static Table1 getTable1() {
        if (ref == null) {
            synchedInitialize();
        }
        return ref;
    }

    private static synchronized void synchedInitialize() {
        if (ref == null) {
            ref = new Table1();
            ref.initialize();
        }
    }
}

public void reinit() { needsInit = true; }

private synchronized void initialize() {
    . . .
    needsInit = false;
}

public int lookup(int i) {
    if (needsInit) {
        this.initialize();
    }
    return theValues[i].getX() + theValues[i].getY();
    . . .
}
Analysis on On-line Purchasing System

- Start from models of individual threads
  - Systematically trace all the possible interleaving of threads
  - Like hand-executing all possible sequences of execution, but automated

- Analysis begins by constructing an FSM model of each individual thread.
Analysis (Continued)

- Java threading rules:
  - When one thread has obtained a monitor lock, the other thread cannot obtain the same lock

- Locking
  - Prevents threads from concurrently calling initialize
  - Does not prevent possible race condition between threads executing the lookup method

- Tracing possible executions by hand is completely impractical.
- Use a finite state verification using the SPIN model checker
proctype Lookup(int id) {
if :: (needsInit) ->
  atomic { ! locked  -> locked = true; };
if :: (needsInit) ->
  assert (! modifying);
  modifying = true;
  /* Initialization happens here */
  modifying = false ;
  needsInit = false;
:: (! needsInit) ->
  skip;
fi;
locked = false ;
fi;
assert (! modifying);}
Run SPIN and Output

• Spin
  – Depth-first search of possible executions of the model
  – Explores 51 states and 92 state transitions in 0.16 seconds
  – Finds a sequence of 17 transitions from the initial state of the model to a state in which one of the assertions in the model evaluates to false

Depth=10 States=51 Transitions=92 Memory=2.302
pan: assertion violated  !(modifying) (at depth 17)
pan: wrote pan_in.trail
(Spin Version 4.2.5 -- 2 April 2005)
...
0.16 real  0.00 user  0.03 sys
Counterexample: Interpret the Output

```
(a) public init lookup(int i)
    if (needsInit) {
        synchronized(this) {
            if (needsInit) {
                this.initialize();
            }
        }
    }

(b) public void reinit()
    {
        needsInit = true;
    }
```

States (f) and (d)

Read/write Race condition

... return
    theValues[i].getX()
    + theValues[i].getY();

...
The State Space Explosion Problem

- Dining philosophers - looking for deadlock with SPIN

  5 phils+forks | 145 states
  deadlock found

  10 phils+forks | 18,313 states
  error trace too long to be useful

  15 phils+forks | 148,897 states
  error trace too long to be useful

- Team Practice and Homework!!!
  - From 2015
The Model Correspondence Problem

- Verifying correspondence between model and program
  - Extract the model from the source code with verified procedures
    - Blindly mirroring all details → state space explosion
    - Omitting crucial detail → “false alarm” reports
  - Produce the source code automatically from the model
    - Most applicable within well-understood domains
  - Conformance testing
    - Combination of FSV and testing is a good tradeoff
Granularity of Modeling

(a)

\( i = i + 1 \)

(b)

\( t = i; \)

(c)

\( i = t; \)

(d)

\( i = i + 1 \)

(w)

\( u = i; \)

(x)

\( u = u + 1; \)

(y)

\( i = u; \)

(z)

\( i = i + 1 \)

(d)

\( i = i + 1 \)

(z)
Analysis of Different Models

- We can find the race only with fine-grain models.

RacerP

(a) \( t = i; \)
(b) \( t = t+1; \)
(c) \( i = t; \)
(d) 

RacerQ

(w) \( u = i; \)
(x) \( u = u+1; \)
(y) \( i = u; \)
(z) 

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Looking for Appropriate Granularity

• Compilers may rearrange the order of instruction.
  – A simple store of a value into a memory cell may be compiled into a store into a local register, with the actual store to memory appearing later.
  – Two loads or stores to different memory locations may be reordered for reasons of efficiency.
  – Parallel computers may place values initially in the cache memory of a local processor, and only later write into a memory area.

• Even representing each memory access as an individual action is not always sufficient.

• Example: Double-check idiom only for lazy initialization
  – Spin assumes that memory accesses occur in the order given in the PROMELA program, and we code them in the same order as the Java program.
  – But, Java does not guarantee that they will be executed in that order.
  – And, SPIN would find a flaw.
Intentional Models

• Enumerating all reachable states is a limiting factor of finite state verification.

• We can reduce the space by using intentional (symbolic) representations.
  – describe sets of reachable states without enumerating each one individually

• Example (set of Integers)
  – Enumeration {2, 4, 6, 8, 10, 12, 14, 16, 18}
  – Intentional representation: \( \{ x \in \mathbb{N} \mid x \mod 2 = 0 \text{ and } 0 < x < 20 \} \)
    ← “characteristic function”

• Intentional models do not necessarily grow with the size of the set they represent
OBDD: A Useful Intentional Model

• OBDD (Ordered Binary Decision Diagram)
  – A compact representation of Boolean functions

• Characteristic function for transition relations
  – Transitions = pairs of states
  – Function from pairs of states to Booleans is true, if there is a transition between the pair.
  – Built iteratively by breadth-first expansion of the state space:
    • Create a representation of the whole set of states reachable in k+1 steps from the set of states reachable in k steps
    • OBDD stabilizes when all the transitions that can occur in the next step are already represented in the OBDD.
From OBDD to Symbolic Checking

- Intentional representation itself is not enough.
- We must have an algorithm for determining whether it satisfies the property we are checking.

- Example: A set of communicating state machines using OBDD
  - To represent the transition relation of a set of communicating state machines
  - To model a class of temporal logic specification formulas

- Combine OBDD representations of model and specification to produce a representation of just the set of transitions leading to a violation of the specification
  - If the set is empty, the property has been verified.
Representing Transition Relations as Boolean Functions

- \( a \Rightarrow b \) and \( c \)
  
  \( \neg(a) \text{ or } (b \text{ and } c) \)

- BDD is a decision tree that has been transformed into an acyclic graph by merging nodes leading to identical sub-trees.
Representing Transition Relations as Boolean Functions: Steps

A. Assign a label to each state
B. Encode transitions
C. The transition tuples correspond to paths leading to true, and all other paths lead to false.
Intentional vs. Explicit Representations

• Worst case:
  – Given a large set $S$ of states,
  – a representation capable of distinguishing each subset of $S$ cannot be more compact on average than the representation that simply lists elements of the chosen subset.

• Intentional representations work well when they exploit structure and regularity of the state space.
Model Refinement

- Construction of finite state models
  - Should balance precision and efficiency
- Often the first model is unsatisfactory
  - Report potential failures that are obviously impossible
  - Exhaust resources before producing any result

- Minor differences in the model can have large effects on tractability of the verification procedure.

- Finite state verification as iterative process is required.
Iteration Process

- Construct an initial model
- Attempt verification
  - Exhusts computational resources
  - Spurious results
- Abstract the model further
- Make the model more precise
Refinement 1: Adding Details to the Model

\[ M_1 \models P \]  \hspace{1cm} \text{Initial (coarse grain) model}\n
(The counter example that violates P is possible in \( M_1 \), but does not correspond to an execution of the real program.)

\[ M_2 \models P \]  \hspace{1cm} \text{Refined (more detailed) model}\n
(the counterexample above is not possible in \( M_2 \), but a new counterexamples violates \( M_2 \), and does not correspond to an execution of the real program too.)

\[ \text{.....} \]

\[ M_k \models P \]  \hspace{1cm} \text{Refined (final) model}\n
(the counter example that violates P in \( M_k \) corresponds to an execution in the real program.)
Refinement 2: Add Premises to the Property

Initial (coarse grain) model

\[ M \models P \]

Add a constraint \( C_1 \) that eliminates the bogus behavior

\[ M \models C_1 \Rightarrow P \]

\[ M \models (C_1 \text{ and } C_2) \Rightarrow P \]

....

Until the verification succeeds or produces a valid counter example
Data Model Verification and Relational Algebra

- Another application of FSV, besides concurrent systems

- Many information systems are characterized by
  - Simple logic and algorithms
  - Complex data structures

- Key element of these systems is the data model
  (UML class and object diagrams + OCL assertions)
  = Sets of data and relations among them

- The challenge is to prove that
  - Individual constraints are consistent.
  - They ensure the desired properties of the system as a whole.
An Example: Simple Web Site

• A set of pages divided among three kinds of pages
  – Unrestricted pages: freely accessible
  – Restricted pages: accessible only to registered users
  – Maintenance pages: inaccessible to both sets of users

• A set of users:
  – administrator, registered, and unregistered

• A set of links relations among pages
  – Private links lead to restricted pages
  – Public links lead to unrestricted pages
  – Maintenance links lead to maintenance pages

• A set of access rights relations between users and pages
  – Unregistered users can access only unrestricted pages
  – Registered users can access both restricted and unrestricted pages
  – Administrator can access all pages including maintenance pages
Data Model of the Simple Web Site

LEGEND

A

↑

B

Set B specializes set A

A

r

B

There is a relation r between sets A and B
module WebSite

// Pages include three disjoint sets of links
sig Page {disj linksPriv, linksPub, linksMain: set Page }

// Each type of link points to a particular class of page
fact connPub {all p:Page, s: Site | p.linksPub in s.unres }
fact connPriv {all p:Page, s: Site | p.linksPriv in s.res }
fact connMain {all p:Page, s: Site | p.linksMain in s.main }

// Self loops are not allowed
fact noSelfLoop {no p:Page | p in p.linksPriv+p.linksPub+p.linksMain }
Relational Algebra Specification (Alloy) for User

// Users are characterized by the set of pages that they can access
sig User { pages: set Page }

// Users are partitioned into three sets
part sig Administrator, Registered, Unregistered extends User {}

// Unregistered users can access only the home page, and unrestricted pages
fact accUnregistered {
  all u: Unregistered, s: Site|u.pages = (s.home+s.unres)
}

// Registered users can access the home page, restricted and unrestricted pages
fact accRegistered {
  all u: Registered, s: Site|u.pages = (s.home+s.res+s.unres)
}

// Administrators can access all pages
fact accAdministrator {
  all u: Administrator, s: Site|
  u.pages = (s.home+s.res+s.unres+s.main)
}
Analysis of the Relational Algebra Specifications

- **Overconstrained** specifications are not satisfiable by any implementation.
- **Underconstrained** specifications allow undesirable implementations.

- Specifications identify infinite sets of solutions.
  - Therefore, properties of a relational specification are undecidable.

- A (counter) example that invalidates a property can be found within a finite set of small models.
  - Then, we can verify a specification over a finite set of solutions by limiting the cardinality of the sets.
Checking a Finite Set of Solutions

- If an example is found,
  - There are no logical contradictions in the model.
  - The solution is not overconstrained.

- If no counterexample of a property is found,
  - No reasonably small solution (property violation) exists.
  - BUT, NOT that NO solution exists.
  - We depend on a “small scope hypothesis”: Most bugs that can cause failure with large collections of objects can also cause failure with very small collections. (so it’s worth looking for bugs in small collections even if we can’t afford to look in big ones)
Analysis of the Simple Web Site Specification

Cardinality limit: Consider up to 5 objects of each type

run init for 5

// Can unregistered users visit all unrestricted pages?
assert browsePub { all p: Page, s: Site | p in s.unres implies s.home in p.* linksPub }
check browsePub for 3

Property to be checked

Transitive closure (including home)
Counterexample:

- Unregistered User_2 cannot visit the unrestricted page page_2.
- The only path from the home page to page_2 goes through the restricted page page_0.
- The property is violated because unrestricted browsing paths can be interrupted by restricted pages or pages under maintenance.
Correcting the Specification

- We can modified the problem by eliminating public links from maintenance or reserved pages:

  \[
  \textbf{fact} \ \text{descendant} \ 
  \begin{aligned}
  &\text{all } p: \text{Pages}, s: \text{Site} | p \text{ in } s.\text{main} + s.\text{res} \\
  &\quad \implies \text{no } p. \text{links}.\text{linkPub}
  \end{aligned}
  \]

- Analysis would find no counterexample of cardinality 3.
- We cannot conclude that no larger counter-example exists, but we may be satisfied that there is no reason to expect this property to be violated only in larger models.
Summary

- Finite state verification is complementary to testing.
  - Can find bugs that are extremely hard to test for
    - Example: race conditions that happen very rarely, under conditions that are hard to control
  - But is limited in scope
    - Cannot be used to find all kinds of errors

- Checking models can be (and is) automated
- But designing good models is challenging.
  - Requires careful consideration of abstraction, granularity, and the properties to be checked
  - Often requires a cycle of model / check / refine until a useful result is obtained
Part III. Problems and Methods
Chapter 9.
Test Case Selection and Adequacy
Learning Objectives

• Understand the purpose of defining test adequacy criteria and their limitations
• Understand basic terminology of test selection and adequacy
• Know some sources of information commonly used to define adequacy criteria
• Understand how test selection and adequacy criteria are used
Overview

• What we would like to know is
  – A real way of measuring effectiveness of testing
  – “If the system passes an adequate suite of test cases, then it must be correct.”

• But that’s impossible.
  – The adequacy of test suites is provably undecidable.

• Therefore, we’ll have to settle on weaker proxies for adequacy.
# Source of Test Specification

<table>
<thead>
<tr>
<th>Testing</th>
<th>Other names</th>
<th>Source of test specification</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Functional Testing</strong></td>
<td>Black box testing</td>
<td>Software specification</td>
</tr>
<tr>
<td></td>
<td>Specification-based testing</td>
<td>If specification requires robust recovery from power failure, test obligations should include simulated power failure.</td>
</tr>
<tr>
<td><strong>Structural Testing</strong></td>
<td>White box testing</td>
<td>Source code</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Traverse each program loop one or more times</td>
</tr>
<tr>
<td><strong>Model-based Testing</strong></td>
<td>Models of system</td>
<td>Models of system</td>
</tr>
<tr>
<td></td>
<td>• Models used in specification or design</td>
<td>• Models derived from source code</td>
</tr>
<tr>
<td></td>
<td>Exercise all transitions in communication protocol model</td>
<td></td>
</tr>
<tr>
<td><strong>Fault-based Testing</strong></td>
<td>Hypothesized faults, common bugs</td>
<td>Check for buffer overflow handling (common vulnerability) by testing on very large inputs</td>
</tr>
</tbody>
</table>
Terminologies in Testing

<table>
<thead>
<tr>
<th>Terms</th>
<th>Descriptions</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Test case</strong></td>
<td>a set of inputs, execution conditions, and a pass/fail criterion</td>
</tr>
<tr>
<td><strong>Test case specification</strong></td>
<td>a requirement to be satisfied by one or more test cases</td>
</tr>
<tr>
<td>(Test specification)</td>
<td></td>
</tr>
<tr>
<td><strong>Test obligation</strong></td>
<td>a partial test case specification, requiring some property deemed</td>
</tr>
<tr>
<td></td>
<td>important to thorough testing</td>
</tr>
<tr>
<td><strong>Test suite</strong></td>
<td>a set of test cases</td>
</tr>
<tr>
<td><strong>Test</strong> (Test execution)</td>
<td>the activity of executing test cases and evaluating their results</td>
</tr>
<tr>
<td><strong>Adequacy criterion</strong></td>
<td>a predicate that is true (satisfied) or false of a ⟨program, test suite⟩ pair</td>
</tr>
</tbody>
</table>
Adequacy Criteria

- Adequacy criterion = Set of test obligations

- A test suite satisfies an adequacy criterion, iff
  - All the tests succeed (pass), and
  - Every test obligation in the criterion is satisfied by at least one of the test cases in the test suite.

  - Example:
  - “The statement coverage adequacy criterion is satisfied by test suite S for program P, if each executable statement in P is executed by at least one test case in S, and the outcome of each test execution was pass.”
Satisfiability

- Sometimes no test suite can satisfy a criterion for a given program.
  - Example:
    - Defensive programming style includes “can’t happen” sanity checks.
      - if (z < 0) {
          throw new LogicError (“z must be positive here!”)
      }
    - For this program, no test suite can satisfy statement coverage.

- Two ways of coping with the unsatisfiability of adequacy criteria
  1. Exclude any unsatisfiable obligation from the criterion
  2. Measure the extent to which a test suite approaches an adequacy criterion
Coping with the Unsatisfiability

• Approach A
  – Exclude any unsatisfiable obligation from the criterion
  – Example:
    • Modify statement coverage to require execution only of statements which can be executed
    – But, we can’t know for sure which are executable or not.

• Approach B
  – Measure the extent to which a test suite approaches an adequacy criterion
  – Example
    • If a test suite satisfies 85 of 100 obligations, we have reached 85% coverage.
  – Terms:
    • An adequacy criterion is satisfied or not.
    • A coverage measure is the fraction of satisfied obligations.
Coverage

• Measuring *coverage* (% of satisfied test obligations) can be a useful indicator of
  – Progress toward a thorough test suite (thoroughness of test suite)
  – Trouble spots requiring more attention in testing

• But, coverage is only a proxy for thoroughness or adequacy.
  – It’s easy to improve coverage without improving a test suite (much easier than designing good test cases)
  – The only measure that really matters is (cost-) effectiveness.
Comparing Criteria

• Can we distinguish stronger from weaker adequacy criteria?

• Analytical approach
  – Describe conditions under which one adequacy criterion is provably stronger than another
  – Just a piece of the overall “effectiveness” question
  – Stronger = gives stronger guarantees
    \[\rightarrow \textbf{Subsumes relation}\]
Subsumes Relation

- Test adequacy criterion $A$ subsumes test adequacy criterion $B$ iff, for every program $P$, every test suite satisfying $A$ with respect to $P$ also satisfies $B$ with respect to $P$.
  - E.g. Exercising all program branches (branch coverage) subsumes exercising all program statements.

- A common analytical comparison of closely related criteria
  - Useful for working from easier to harder levels of coverage, but not a direct indication of quality
THEORETICAL CRITERIA

Path Testing

Boundary interior testing

Compound condition testing

Cyclomatic testing

MC/DC testing

LCSAJ testing

Branch and condition testing

Branch testing

Basic condition testing

Loop boundary testing

Statement testing
Use of Adequacy Criteria

1. Test selection approaches (Selection)
   – Guidance in devising a thorough test suite
     • E.g. A specification-based testing criterion may suggest test cases covering representative combinations of values.

2. Revealing missing tests (Measurement)
   – Post hoc analysis: What might I have missed with this test suite?

• Often in combination
   – Design test suite from specifications, then use structural criterion (e.g. coverage of all branches) to highlight missed logic
Summary

• Adequacy criteria provide a way to define a notion of “thoroughness” in a test suite.
  – But, they don’t offer guarantees.
  – More like rules to highlight inadequacy

• Adequacy criteria are defined in terms of “covering” some information
  – Derived from many sources (specs, code, models, etc.)

• Adequacy criteria may be used for selection as well as measurement.
  – But, an aid to thoughtful test design, not a substitute
Chapter 10.
Functional Testing
Learning Objectives

- Understand the rationale for systematic (non-random) selection of test cases
- Understand why functional test selection is a primary, base-line technique
- Distinguish functional testing from other systematic testing techniques
Functional Testing

- **Functional testing**
  - Deriving test cases from program specifications
  - ‘Functional’ refers to the source of information used in test case design, not to what is tested.

- Also known as:
  - Specification-based testing (from specifications)
  - Black-box testing (no view of source code)

- Functional specification = description of intended program behavior
  - Formal or informal
Systematic testing vs. Random testing

- **Random (uniform) testing**
  - Pick possible inputs uniformly
  - Avoids designer’s bias
  - But, treats all inputs as equally valuable

- **Systematic (non-uniform) testing**
  - Try to select inputs that are especially valuable
  - Usually by choosing representatives of classes that are apt to fail often or not at all

- Functional testing is a systematic (partition-based) testing strategy.
Why Not Random Testing?

• Due to non-uniform distribution of faults
  – Example:
    • Java class “roots” applies quadratic equation \( x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \)
  – Supposed an incomplete implementation logic:
    • Program does not properly handle the case in which \( b^2 - 4ac = 0 \) and \( a=0 \)
  – Failing values are sparse in the input space: needles in a very big haystack
  – Random sampling is unlikely to choose \( a=0 \) and \( b=0 \).
Purpose of Testing

• Our goal is to find needles and remove them from hay.
  → Look systematically (non-uniformly) for needles !!!
  – We need to use everything we know about needles.
    • E.g. Are they heavier than hay? Do they sift to the bottom?

• To estimate the proportion of needles to hay
  → Sample randomly !!!
  – Reliability estimation requires unbiased samples for valid statistics.
  – But that’s not our goal.
Systematic Partition Testing

- Failure (valuable test case)
- No failure

Failures are sparse in the space of possible inputs.

But, dense in some parts of the space

The space of possible input values (the haystack)

If we systematically test some cases from each part, we will include the dense parts.

Functional testing is one way of drawing pink lines to isolate regions with likely failures.
Principles of Systematic Partitioning

• Exploit some knowledge to choose samples that are more likely to include “special” or “trouble-prone” regions of the input space
  – Failures are sparse in the whole input space.
  – But, we may find regions in which they are dense.

• (Quasi-) Partition testing: separates the input space into classes whose union is the entire space

• Desirable case: Each fault leads to failures that are dense (easy to find) in some class of inputs
  – Sampling each class in the quasi-partition selects at least one input that leads to a failure, revealing the fault.
  – Seldom guaranteed; We depend on experience-based heuristics.
A Systematic Approach: Functional Testing

• Functional testing uses the specification (formal or informal) to partition the input space.
  – E.g. Specification of “roots” program suggests division between cases with zero, one, and two real roots.

• Test each category and boundaries between categories
  – No guarantees, but experience suggests failures often lie at the boundaries. (as in the “roots” program)

• Functional Testing is a base-line technique for designing test cases.
Functional Testing

- The base-line technique for designing test cases
  - Timely
    - Often useful in refining specifications and assessing testability before code is written
  - Effective
    - Find some classes of fault (e.g. missing logic) that can elude other approaches
  - Widely applicable
    - To any description of program behavior serving as specification
    - At any level of granularity from module to system testing
  - Economical
    - Typically less expensive to design and execute than structural (code-based) test cases
Functional Test vs. Structural Test

• Different testing strategies are most effective for different classes of faults.

• Functional testing is best for missing logic faults.
  – A common problem: Some program logic was simply forgotten.
  – Structural (code-based) testing will never focus on code that isn’t there.

• Functional test applies at all granularity levels
  – Unit (from module interface spec)
  – Integration (from API or subsystem spec)
  – System (from system requirements spec)
  – Regression (from system requirements + bug history)

• Structural test design applies to relatively small parts of a system
  – Unit and integration testing
Main Steps of Functional Program Testing

- **Functional specifications**
  - Identify independently testable features
  - Derive a model
  - Generate test case specifications
  - Generate test cases
  - Instantiate tests
  - Scaffolding

- **Independentely Testable Feature**
  - Identify representative values
  - Design of a model

- **Representative Values**
  - Semantic Constraint, Combinational Selection, Exhaustive Enumeration, Random Selection

- **Model**
  - Finite State Machine, Grammar, Algebraic Specification, Logic Specification, CFG / DFG
  - Test selection criteria

- **Test Case Specification**
  - Test selection criteria

- **Test Cases**
  - Instantiation of tests
Functional Specifications

Identify Independently Testable Features

Independently Testable Feature

Identify Representative Values

Derive a Model

Model

Finite State Machine Grammar
Algebraic Specification
Logic Specification
Control Data Flow Graph

Generate Test Case Specifications

Test Case Specifications

Generate Test Cases

Test Cases

Generate Test Cases

Test Selection Criteria

Semantic Constraints
Combinatorial Selection
Exhaustive Enumeration
Random Selection

Manual Mapping
Symbolic Execution
A posteriori Satisfaction

Test Cases

Instantiate Tests

Scaffolding
From Specifications to Test Cases

1. Identify independently testable features
   - If the specification is large, break it into independently testable features.

2. Identify representative classes of values, or derive a model of behavior
   - Often simple input/output transformations don’t describe a system.
   - We use models in program specification, in program design, and in test design too.

3. Generate test case specifications
   - Typically, combinations of input values or model behaviors

4. Generate test cases and instantiate tests
Summary

• Functional testing (generating test cases from specifications) is a valuable and flexible approach to software testing.
  – Applicable from very early system specifications right through module specifications

• Partition testing suggests dividing the input space into equivalent classes.
  – Systematic testing is intentionally non-uniform to address special cases, error conditions and other small places.
  – Dividing a big haystack into small and hopefully uniform piles where the needles might be concentrated
Chapter 11.
Combinatorial Testing
Learning Objectives

• Understand three key ideas in combinatorial approaches
  – Category-partition testing
  – Pairwise testing
  – Catalog-based testing
Overview

- Combinatorial testing identifies distinct attributes that can be varied.
  - In data, environment or configuration
  - Example:
    - Browser could be “IE” or “Firefox”
    - Operating system could be “Vista”, “XP” or “OSX”

- Combinatorial testing systematically generates combinations to be tested.
  - Example:
    - IE on Vista, IE on XP, Firefox on Vista, Firefox on OSX, etc.

- Rationale:
  - Test cases should be varied and include possible “corner cases”.
Key Ideas in Combinatorial Approaches

1. Category-partition testing
   - Separate (manual) identification of values that characterize the input space from (automatic) generation of combinations for test cases

2. Pairwise testing
   - Systematically test interactions among attributes of the program input space with a relatively small number of test cases

3. Catalog-based testing
   - Aggregate and synthesize the experience of test designers in a particular organization or application domain, to aid in identifying attribute values
1. Category-Partition Testing

1. Decompose the specification into independently testable features
   – for each feature, identify parameters and environment elements
   – for each parameter and environment element, identify elementary characteristics (→ categories)

2. Identify representative values
   – for each characteristic(category), identify classes of values
     • normal values
     • boundary values
     • special values
     • error values

3. Generate test case specifications
An Example: “Check Configuration”

- In the Web site of a computer manufacturer, *i.e. Dell*, ‘checking configuration’ checks the validity of a computer configuration.
  - Two parameters:
    - Model
    - Set of Components
Informal Specification of ‘Model’

**Model:** A model identifies a specific product and determines a set of constraints on available components. Models are characterized by logical slots for components, which may or may not be implemented by physical slots on a bus. Slots may be required or optional. Required slots must be assigned with a suitable component to obtain a legal configuration, while optional slots may be left empty or filled depending on the customer’s needs.

**Example:** The required “slots” of the Chipmunk C20 laptop computer include a screen, a processor, a hard disk, memory, and an operating system. (Of these, only the hard disk and memory are implemented using actual hardware slots on a bus.) The optional slots include external storage devices such as a CD/DVD writer.
Informal Specification of ‘Set of Component’

**Set of Components:** A set of (slot, component) pairs, corresponds to the required and optional slots of the model. A component is a choice that can be varied within a model, and which is not designed to be replaced by the end user. Available components and a default for each slot is determined by the model. The special value empty is allowed (and may be the default selection) for optional slots. In addition to being compatible or incompatible with a particular model and slot, individual components may be compatible or incompatible with each other.

**Example:** The default configuration of the Chipmunk C20 includes 20 gigabytes of hard disk; 30 and 40 gigabyte disks are also available. (Since the hard disk is a required slot, empty is not an allowed choice.) The default operating system is RodentOS 3.2, personal edition, but RodentOS 3.2 mobile server edition may also be selected. The mobile server edition requires at least 30 gigabytes of hard disk.
Step 1: Identify Independently Testable Features and Parameter Characteristics

• Choosing categories
  – No hard-and-fast rules for choosing categories!
  – Not a trivial task

• Categories reflect test designer's judgment.
  – Which classes of values may be treated differently by an implementation.

• Choosing categories well requires experience and knowledge of the application domain and product architecture.
## Identify Independently Testable Units

<table>
<thead>
<tr>
<th>Model</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Model number</td>
</tr>
<tr>
<td></td>
<td>Number of required slots for selected model (#SMRS)</td>
</tr>
<tr>
<td></td>
<td>Number of optional slots for selected model (#SMOS)</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Components</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Correspondence of selection with model slots</td>
</tr>
<tr>
<td></td>
<td>Number of required components with selection ≠ empty</td>
</tr>
<tr>
<td></td>
<td>Required component selection</td>
</tr>
<tr>
<td></td>
<td>Number of optional components with selection ≠ empty</td>
</tr>
<tr>
<td></td>
<td>Optional component selection</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Product Database</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Number of models in database (#DBM)</td>
</tr>
<tr>
<td></td>
<td>Number of components in database (#DBC)</td>
</tr>
</tbody>
</table>
Step 2: Identify Representative Values

- Identify representative classes of values for each of the categories

- Representative values may be identified by applying
  - **Boundary value testing**
    - Select extreme values within a class
    - Select values outside but as close as possible to the class
    - Select interior (non-extreme) values of the class
  - **Erroneous condition testing**
    - Select values outside the normal domain of the program
Representative Values: Model

- Model number
  - Malformed
  - Not in database
  - Valid

- Number of required slots for selected model (#SMRS)
  - 0
  - 1
  - Many

- Number of optional slots for selected model (#SMOS)
  - 0
  - 1
  - Many
Representative Values: Components

- Correspondence of selection with model slots
  - Omitted slots
  - Extra slots
  - Mismatched slots
  - Complete correspondence

- Number of required components with non empty selection
  - 0
  - < number required slots
  - = number required slots

- Required component selection
  - Some defaults
  - All valid
  - ≥ 1 incompatible with slots
  - ≥ 1 incompatible with another selection
  - ≥ 1 incompatible with model
  - ≥ 1 not in database
Representative Values: Components

- Number of optional components with non empty selection
  - 0
  - < #SMOS
  - = #SMOS

- Optional component selection
  - Some defaults
  - All valid
  - ≥ 1 incompatible with slots
  - ≥ 1 incompatible with another selection
  - ≥ 1 incompatible with model
  - ≥ 1 not in database
Representative Values: Product Database

- Number of models in database (#DBM)
  - 0
  - 1
  - Many

- Number of components in database (#DBC)
  - 0
  - 1
  - Many

- Note 0 and 1 are unusual (special) values.
  - They might cause unanticipated behavior alone or in combination with particular values of other parameters.
Step 3: Generate Test Case Specifications

- A combination of values for each category corresponds to a test case specification.
  - In the example, we have 314,928 test cases.
  - Most of which are impossible.
  - Example: zero slots and at least one incompatible slot

- Need to introduce constraints in order to
  - Rule out impossible combinations, and
  - Reduce the size of the test suite, if too large

  - Example:
    - Error constraints
    - Property constraints
    - Single constraints
Error Constraints

- [error] indicates a value class that corresponds to an erroneous values.
  - Need to be tried only once

- Error value class
  - No need to test all possible combinations of errors, and one test is enough.

<table>
<thead>
<tr>
<th>Error</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Malformed</td>
<td>[error]</td>
</tr>
<tr>
<td>Not in database</td>
<td>[error]</td>
</tr>
<tr>
<td>Valid</td>
<td></td>
</tr>
</tbody>
</table>

Correspondence of selection with model slots:
- Omitted slots [error]
- Extra slots   [error]
- Mismatched slots [error]
- Complete correspondence

Number of required comp. with non empty selection:
- 0 [error]
- < number of required slots [error]

Required comp. selection:
- ≥ 1 not in database [error]

Number of models in database (#DBM):
- 0 [error]

Number of components in database (#DBC):
- 0 [error]

**Error constraints reduce test suite from 314,928 to 2,711 test cases**
Property Constraints

- Constraint [property] [if-property] rule out invalid combinations of values.
  - [property] groups values of a single parameter to identify subsets of values with common properties.
  - [if-property] bounds the choices of values for a category that can be combined with a particular value selected for a different category.
Property Constraints

Number of required slots for selected model (#SMRS)

1  [property RSNE]
Many [property RSNE] [property RSMANY]

Number of optional slots for selected model (#SMOS)

1  [property OSNE]
Many [property OSNE] [property OSMANY]

Number of required comp. with non empty selection

0  [if RSNE] [error]
< number required slots  [if RSNE] [error]
= number required slots  [if RSMANY]

Number of optional comp. with non empty selection

< number required slots  [if OSNE]
= number required slots  [if OSMANY]

from 2,711 to 908 test cases
Single Constraints

• [single] indicates a value class that test designers choose to test only once to reduce the number of test cases.

• Example
  – Value some default for required component selection and optional component selection may be tested only once despite not being an erroneous condition.

• Note
  – Single and error have the same effect but differ in rationale.
  – Keeping them distinct is important for documentation and regression testing.
Single Constraints

Number of required slots for selected model (#SMRS)
0 [single]
1 [property RSNE] [single]

Number of optional slots for selected model (#SMOS)
0 [single]
1 [single] [property OSNE]

Required component selection
Some default [single]

Optional component selection
Some default [single]

Number of models in database (#DBM)
1 [single]

Number of components in database (#DBC)
1 [single]

from 908 to 69 test cases
## Check Configuration – Summary of Categories

### Parameter Model
- **Model number**
  - Malformed [error]
  - Not in database [error]
  - Valid
- **Number of required slots for selected model (#SMRS)**
  - 0 [single]
  - 1 [property RSNE] [single]
  - Many [property RSNE] [property RSMANY]
- **Number of optional slots for selected model (#SMOS)**
  - 0 [single]
  - 1 [property OSNE] [single]
  - Many [property OSNE] [property OSMANY]

### Environment Product database
- **Number of models in database (#DBM)**
  - 0 [error]
  - 1 [single]
  - Many
- **Number of components in database (#DBC)**
  - 0 [error]
  - 1 [single]
  - Many

### Parameter Component
- **Correspondence of selection with model slots**
  - Omitted slots [error]
  - Extra slots [error]
  - Mismatched slots [error]
  - Complete correspondence
- **# of required components (selection ≠ empty)**
  - 0 [if RSNE] [error]
  - < #SMOS [if RSNE] [error]
  - = #SMOS [if RSMANY]
- **Required component selection**
  - Some defaults [single]
  - All valid
  - ≥ 1 incompatible with slots
  - ≥ 1 incompatible with another selection
  - ≥ 1 incompatible with model
  - ≥ 1 not in database [error]
- **# of optional components (selection ≠ empty)**
  - 0 [error]
  - < #SMOS [if OSNE]
  - = #SMOS [if OSMANY]
- **Optional component selection**
  - Some defaults [single]
  - All valid
  - ≥ 1 incompatible with slots
  - ≥ 1 incompatible with another selection
  - ≥ 1 incompatible with model
  - ≥ 1 not in database [error]
Category-Partitioning Testing, in Summary

- Category partition testing gives us systematic approaches to
  - Identify characteristics and values (the creative step)
  - Generate combinations (the mechanical step)

- But, test suite size grows very rapidly with number of categories.
- Pairwise (and n-way) combinatorial testing is a non-exhaustive approach.
  - Combine values systematically but not exhaustively
2. Pairwise Combination Testing

- Category partition works well when intuitive constraints reduce the number of combinations to a small amount of test cases.
  - Without many constraints, the number of combinations may be unmanageable.

- Pairwise combination
  - Instead of exhaustive combinations
  - Generate combinations that efficiently cover all pairs (triples,...) of classes
  - Rationale:
    - Most failures are triggered by single values or combinations of a few values.
    - Covering pairs (triples,...) reduces the number of test cases, but reveals most faults.
An Example: Display Control

- No constraints reduce the total number of combinations 432 (3x4x3x4x3) test cases, if we consider all combinations.

<table>
<thead>
<tr>
<th>Display Mode</th>
<th>Language</th>
<th>Fonts</th>
<th>Color</th>
<th>Screen size</th>
</tr>
</thead>
<tbody>
<tr>
<td>full-graphics</td>
<td>English</td>
<td>Minimal</td>
<td>Monochrome</td>
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</tr>
<tr>
<td>limited-bandwidth</td>
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<td>Document-loaded</td>
<td>16-bit</td>
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<tr>
<td></td>
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</tr>
</tbody>
</table>
## Pairwise Combination: 17 Test Cases

<table>
<thead>
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Adding Constraints

• Simple constraints
  – Example: “Color monochrome not compatible with screen laptop and full size” can be handled by considering the case in separate tables.

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Pairwise Combination Testing, in Summary

- Category-partition approach gives us
  - Separation between (manual) identification of parameter characteristics and values, and (automatic) generation of test cases that combine them
  - Constraints to reduce the number of combinations

- Pairwise (or n-way) testing gives us
  - Much smaller test suites, even without constraints
  - But, we can still use constraints.

- We still need help to make the manual step more systematic.
3. Catalog-based Testing

- Deriving value classes requires human judgment.
- Therefore, gathering experience in a systematic collection can
  - Speed up the test design process
  - Routinize many decisions, better focusing human effort
  - Accelerate training and reduce human error

- **Catalogs** capture the experience of test designers by listing important cases for each possible type of variable.
  - Example: If the computation uses an integer variable, a catalog might indicate the following relevant cases
    - The element immediately preceding the lower bound
    - The lower bound of the interval
    - A non-boundary element within the interval
    - The upper bound of the interval
    - The element immediately following the upper bound
Catalog-based Testing Process

1. Identify elementary items of the specification
   - Pre-conditions
   - Post-conditions
   - Definitions
   - Variables
   - Operations

2. Derive a first set of test case specifications from pre-conditions, post-conditions and definitions

3. Complete the set of test case specifications using test catalogs
An Example: ‘cgi_decode’

- An informal specification of ‘cgi_decode’

Function `cgi_decode` translates a cgi-encoded string to a plain ASCII string, reversing the encoding applied by the common gateway interface (CGI) of most web servers.

CGI translates spaces to +, and translates most other non-alphanumeric characters to hexadecimal escape sequences.

cgi_decode maps + to spaces, %xy (where x and y are hexadecimal digits) to the corresponding ASCII character, and other alphanumeric characters to themselves.
`cgi_digicode` Input/Output

- **[INPUT]: encoded** A string of characters (the input CGI sequence) containing below and terminated by a null character
  - alphanumeric characters
  - the character +
  - the substring “%xy”, where x and y are hexadecimal digits

- **[OUTPUT]: decoded** A string of characters (the plain ASCII characters corresponding to the input CGI sequence)
  - alphanumeric characters copied into output (in corresponding positions)
  - blank for each ‘+’ character in the input
  - single ASCII character with value xy for each substring “%xy”

- **[OUTPUT]: return value** `cgi_decode` returns
  - 0 for success
  - 1 if the input is malformed
‘cgi_digicode’ Definitions

• Pre-conditions: Conditions on inputs that must be true before the execution
  – Validated preconditions: checked by the system
  – Assumed preconditions: assumed by the system

• Post-conditions: Results of the execution

• Variables: Elements used for the computation

• Operations: Main operations on variables and inputs

• Definitions: Abbreviations
Step 1: Identify Elementary Items of the Specification

**VAR 1 encoded**: a string of ASCII characters
**VAR 2 decoded**: a string of ASCII characters
**VAR 3 return value**: a boolean

**DEF 1** hexadecimal characters, in range ['0' .. '9', 'A' .. 'F', 'a' .. 'f']
**DEF 2** sequences %xy, where x and y are hexadecimal characters
**DEF 3** CGI items as alphanumeric character, or '+', or CGI hexadecimal

**OP 1** Scan the input string encoded

**PRE 1** (Assumed) input string encoded null-terminated string of chars
**PRE 2** (Validated) input string encoded sequence of CGI items

**POST 1** if encoded contains alphanumeric characters, they are copied to the output string
**POST 2** if encoded contains characters +, they are replaced in the output string by ASCII SPACE characters
**POST 3** if encoded contains CGI hexadecimals, they are replaced by the corresponding ASCII characters
**POST 4** if encoded is processed correctly, it returns 0
**POST 5** if encoded contains a wrong CGI hexadecimal (a substring xy, where either x or y are absent or are not hexadecimal digits, cgi_decode returns 1
**POST 6** if encoded contains any illegal character, it returns 1

**VAR 1 encoded**: a string of ASCII characters
Step 2: Derive an Initial Set of Test Case Specifications

- Validated preconditions:
  - Simple precondition (expression without operators)
    - 2 classes of inputs:
      - inputs that satisfy the precondition
      - inputs that do not satisfy the precondition
  - Compound precondition (with AND or OR):
    - apply modified condition/decision (MC/DC) criterion

- Assumed precondition:
  - apply MC/DC only to “OR preconditions”

- Postconditions and Definitions:
  - if given as conditional expressions, consider conditions as if they were validated preconditions
Test Cases from PRE

PRE 2 (Validated): the input string **encoded** is a sequence of CGI items
- TC-PRE2-1: **encoded** is a sequence of CGI items
- TC-PRE2-2: **encoded** is not a sequence of CGI items

POST 1: if **encoded** contains alphanumeric characters, they are copied in the output string in the corresponding position
- TC-POST1-1: **encoded** contains alphanumeric characters
- TC-POST1-2: **encoded** does not contain alphanumeric characters

POST 2: if **encoded** contains characters +, they are replaced in the output string by ASCII SPACE characters
- TC-POST2-1: **encoded** contains character +
- TC-POST2-2: **encoded** does not contain character +
Test Cases from POST

POST 3: if encoded contains CGI hexadecimals, they are replaced by the corresponding ASCII characters
   - TC-POST3-1 Encoded: contains CGI hexadecimals
   - TC-POST3-2 Encoded: does not contain a CGI hexadecimal

POST 4: if encoded is processed correctly, it returns 0

POST 5: if encoded contains a wrong CGI hexadecimal (a substring xy, where either x or y are absent or are not hexadecimal digits, cgi_decode returns 1
   - TC-POST5-1 Encoded: contains erroneous CGI hexadecimals

POST 6 if encoded contains any illegal character, it returns 1
   - TC-POST6-1 Encoded: contains illegal characters
Step 3: Complete the Test Case Specification using Catalog

- Scan the catalog sequentially
  - For each element of the catalog,
    - Scan the specifications and apply the catalog entry
- Delete redundant test cases

- **Catalog**
  - List of kinds of elements that can occur in a specification
  - Each catalog entry is associated with a list of generic test case specifications.

- Example: Catalog entry Boolean
  - Two test case specifications: true, false
  - Label in/out indicate if applicable only to input, output, both
A Simple Test Catalog

- **Boolean**
  - True [in/out]
  - False [in/out]

- **Enumeration**
  - Each enumerated value [in/out]
  - Some value outside the enumerated set [in]

- **Range L ... U**
  - L-1 [in]
  - L [in/out]
  - A value between L and U [in/out]
  - U [in/out]
  - U+1 [in]

- **Numeric Constant C**
  - C [in/out]
  - C -1 [in]
  - C +1 [in]
  - Any other constant compatible with C [in]

- **Non-Numeric Constant C**
  - C [in/out]
  - Any other constant compatible with C [in]
  - Some other compatible value [in]

- **Sequence**
  - Empty [in/out]
  - A single element [in/out]
  - More than one element [in/out]
  - Maximum length (if bounded) or very long [in/out]
  - Longer than maximum length (if bounded) [in]
  - Incorrectly terminated [in]

- **Scan with action on elements P**
  - P occurs at beginning of sequence [in]
  - P occurs in interior of sequence [in]
  - P occurs at end of sequence [in]
  - PP occurs continguously [in]
  - P does not occur in sequence [in]
  - pP where p is a proper prefix of P [in]
  - Proper prefix p occurs at end of sequence [in]
Catalog Entry: Boolean

• Boolean
  – True [in/out]
  – False [in/out]

• Application to return value generates 2 test cases already covered by TC-PRE2-1 and TC-PRE2-2.
Catalog Entry: Enumeration

• Enumeration
  – Each enumerated value [in/out]
  – Some value outside the enumerated set [in]

• Applications to CGI item (DEF 3)
  – included in TC-POST1-1, TC-POST1-2, TC-POST2-1, TC-POST2-2, TC-POST3-1, TC-POST3-2

• Applications to improper CGI hexadecimals
  – New test case specifications
    • TC-POST5-2 encoded terminated with “%x”, where x is a hexadecimal digit
    • TC-POST5-3 encoded contains “%ky”, where k is not a hexadecimal digit and y is a hexadecimal digit
    • TC-POST5-4 encoded contains “%xk”, where x is a hexadecimal digit and k is not
  – Old test case specifications can be eliminated if they are less specific than the newly generated cases.
    • TC-POST3-1 encoded contains CGI hexadecimals
    • TC-POST5-1 encoded contains erroneous CGI hexadecimals
Catalog Entries: the Others

We can apply in the same ways.

• range
• numeric constant
• non-numeric constant
• sequence
• scan
### Summary of Generated Test Cases

<table>
<thead>
<tr>
<th>Test Case</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>TC-POST2-1</td>
<td><code>encoded</code> contains <code>+</code></td>
</tr>
<tr>
<td>TC-POST2-2</td>
<td><code>encoded</code> does not contain <code>+</code></td>
</tr>
<tr>
<td>TC-POST3-2</td>
<td><code>encoded</code> does not contain a CGI-hexadecimal</td>
</tr>
<tr>
<td>TC-POST5-2</td>
<td><code>encoded</code> terminated with <code>%x</code></td>
</tr>
<tr>
<td>TC-VAR1-1</td>
<td><code>encoded</code> is the empty sequence</td>
</tr>
<tr>
<td>TC-VAR1-2</td>
<td><code>encoded</code> a sequence containing a single character</td>
</tr>
<tr>
<td>TC-VAR1-3</td>
<td><code>encoded</code> is a very long sequence</td>
</tr>
<tr>
<td>TC-DEF2-1</td>
<td><code>encoded</code> contains <code>%y</code></td>
</tr>
<tr>
<td>TC-DEF2-2</td>
<td><code>encoded</code> contains <code>%0y</code></td>
</tr>
<tr>
<td>TC-DEF2-3</td>
<td><code>encoded</code> contains <code>%xy</code> (x in [1..8])</td>
</tr>
<tr>
<td>TC-DEF2-4</td>
<td><code>encoded</code> contains <code>%9y</code></td>
</tr>
<tr>
<td>TC-DEF2-5</td>
<td><code>encoded</code> contains <code>%:y</code></td>
</tr>
<tr>
<td>TC-DEF2-6</td>
<td><code>encoded</code> contains <code>%@y</code></td>
</tr>
<tr>
<td>TC-DEF2-7</td>
<td><code>encoded</code> contains <code>%Ay</code></td>
</tr>
<tr>
<td>TC-DEF2-8</td>
<td><code>encoded</code> contains <code>%xy</code> (x in [B..E])</td>
</tr>
<tr>
<td>TC-DEF2-9</td>
<td><code>encoded</code> contains <code>%/y</code></td>
</tr>
<tr>
<td>TC-DEF2-10</td>
<td><code>encoded</code> contains <code>%0y</code></td>
</tr>
<tr>
<td>TC-DEF2-11</td>
<td><code>encoded</code> contains <code>%y</code></td>
</tr>
<tr>
<td>TC-DEF2-12</td>
<td><code>encoded</code> contains <code>%xy</code> (x in [b..e])</td>
</tr>
<tr>
<td>TC-DEF2-13</td>
<td><code>encoded</code> contains <code>%xy</code> (y in [B..E])</td>
</tr>
<tr>
<td>TC-DEF2-14</td>
<td><code>encoded</code> contains <code>%xy</code> (y in [b..e])</td>
</tr>
<tr>
<td>TC-DEF2-15</td>
<td><code>encoded</code> contains <code>%xy</code> (y in [b..e])</td>
</tr>
<tr>
<td>TC-DEF2-16</td>
<td><code>encoded</code> contains <code>%xy</code> (y in [B..E])</td>
</tr>
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<td>TC-DEF2-17</td>
<td><code>encoded</code> contains <code>%xy</code> (y in [B..E])</td>
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<td><code>encoded</code> contains <code>%xy</code> (y in [B..E])</td>
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<td><code>encoded</code> contains <code>%xy</code> (y in [B..E])</td>
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<td><code>encoded</code> contains <code>%xy</code> (y in [B..E])</td>
</tr>
<tr>
<td>TC-DEF2-25</td>
<td><code>encoded</code> contains <code>%xy</code> (y in [B..E])</td>
</tr>
<tr>
<td>TC-DEF2-26</td>
<td><code>encoded</code> contains <code>%x</code></td>
</tr>
<tr>
<td>TC-DEF2-27</td>
<td><code>encoded</code> contains <code>%xa</code></td>
</tr>
<tr>
<td>TC-DEF2-28</td>
<td><code>encoded</code> contains <code>%xy</code> (y in [b..e])</td>
</tr>
<tr>
<td>TC-DEF2-29</td>
<td><code>encoded</code> contains <code>%xf</code></td>
</tr>
<tr>
<td>TC-DEF2-30</td>
<td><code>encoded</code> contains <code>%xg</code></td>
</tr>
<tr>
<td>TC-DEF2-31</td>
<td><code>encoded</code> terminates with <code>%</code></td>
</tr>
<tr>
<td>TC-DEF2-32</td>
<td><code>encoded</code> contains <code>%xyz</code></td>
</tr>
<tr>
<td>TC-DEF3-1</td>
<td><code>encoded</code> contains <code>/</code></td>
</tr>
<tr>
<td>TC-DEF3-2</td>
<td><code>encoded</code> contains <code>0</code></td>
</tr>
<tr>
<td>TC-DEF3-3</td>
<td><code>encoded</code> contains <code>c</code> in [1..8]</td>
</tr>
<tr>
<td>TC-DEF3-4</td>
<td><code>encoded</code> contains <code>9</code></td>
</tr>
<tr>
<td>TC-DEF3-5</td>
<td><code>encoded</code> contains <code>:</code></td>
</tr>
<tr>
<td>TC-DEF3-6</td>
<td><code>encoded</code> contains <code>@</code></td>
</tr>
<tr>
<td>TC-DEF3-7</td>
<td><code>encoded</code> contains <code>A</code></td>
</tr>
<tr>
<td>TC-DEF3-8</td>
<td><code>encoded</code> contains <code>c</code> in [B..Y]</td>
</tr>
<tr>
<td>TC-DEF3-9</td>
<td><code>encoded</code> contains <code>Z</code></td>
</tr>
<tr>
<td>TC-DEF3-10</td>
<td><code>encoded</code> contains <code>/</code></td>
</tr>
<tr>
<td>TC-DEF3-11</td>
<td><code>encoded</code> contains <code>%y</code></td>
</tr>
<tr>
<td>TC-DEF3-12</td>
<td><code>encoded</code> contains <code>a</code></td>
</tr>
<tr>
<td>TC-DEF3-13</td>
<td><code>encoded</code> contains <code>c</code> in [B..Y]</td>
</tr>
<tr>
<td>TC-DEF3-14</td>
<td><code>encoded</code> contains <code>z</code></td>
</tr>
<tr>
<td>TC-DEF3-15</td>
<td><code>encoded</code> contains <code>{</code></td>
</tr>
<tr>
<td>TC-OP1-1</td>
<td><code>encoded</code> starts with an alphanumeric character</td>
</tr>
<tr>
<td>TC-OP1-2</td>
<td><code>encoded</code> starts with <code>+</code></td>
</tr>
<tr>
<td>TC-OP1-3</td>
<td><code>encoded</code> starts with <code>%xy</code></td>
</tr>
<tr>
<td>TC-OP1-4</td>
<td><code>encoded</code> terminates with an alphanumeric character</td>
</tr>
<tr>
<td>TC-OP1-5</td>
<td><code>encoded</code> terminates with <code>+</code></td>
</tr>
<tr>
<td>TC-OP1-6</td>
<td><code>encoded</code> terminated with <code>%xy</code></td>
</tr>
<tr>
<td>TC-OP1-7</td>
<td><code>encoded</code> contains two consecutive alphanumeric characters</td>
</tr>
<tr>
<td>TC-OP1-8</td>
<td><code>encoded</code> contains <code>++</code></td>
</tr>
<tr>
<td>TC-OP1-9</td>
<td><code>encoded</code> contains <code>%xy%zw</code></td>
</tr>
<tr>
<td>TC-OP1-10</td>
<td><code>encoded</code> contains <code>%xx%yz</code></td>
</tr>
</tbody>
</table>
What Have We Got from Three Methods?

• From category partition testing:
  – Division into a (manual) step of identifying categories and values, with constraints, and an (automated) step of generating combinations

• From catalog-based testing:
  – Improving the manual step by recording and using standard patterns for identifying significant values

• From pairwise testing:
  – Systematic generation of smaller test suites

• Three ideas can be combined.
Summary

- Requirements specifications typically begin in the form of natural language statements.
  - But, flexibility and expressiveness of natural language is an obstacle to automatic analysis.

- Combinatorial approaches to functional testing consist of
  - A manual step of structuring specifications into set of properties
  - An automatic(-able) step of producing combinations of choices

- Brute force synthesis of test cases is tedious and error prone.
  - Combinatorial approaches decompose brute force work into steps to attack the problem incrementally by separating analysis and synthesis activities that can be quantified and monitored, and partially supported by tools.
Chapter 12.
Structural Testing
Learning Objectives

• Understand rationale for structural testing
  – How structural testing complements functional testing

• Recognize and distinguish basic terms such as adequacy and coverage
• Recognize and distinguish characteristics of common structural criteria
• Understand practical uses and limitations of structural testing
Structural Testing

- Judging test suite thoroughness based on the structure of the program itself
  - Also known as
    - White-box testing
    - Glass-box testing
    - Code-based testing
  - Distinguish from functional (requirements-based, “black-box”) testing

- Structural testing is still testing product functionality against its specification.
  - Only the measure of thoroughness has changed.
Rationale of Structural Testing

• One way of answering the question “What is missing in our test suite?”
  – If a part of a program is not executed by any test case in the suite, faults in that part cannot be exposed.
  – But what’s the ‘part’?
    • Typically, a control flow element or combination
    • Statements (or CFG nodes), Branches (or CFG edges)
    • Fragments and combinations: Conditions, paths

• Structural testing complements functional testing.
  – Another way to recognize cases that are treated differently

• Recalling fundamental rationale
  – Prefer test cases that are treated differently over cases treated the same
No Guarantee

• Executing all control flow elements does not guarantee finding all faults.
  – Execution of a faulty statement may not always result in a failure.
    • The state may not be corrupted when the statement is executed with some data values.
    • Corrupt state may not propagate through execution to eventually lead to failure.

• What is the value of structural coverage?
  – Increases confidence in thoroughness of testing
Structural Testing Complements Functional Testing

• Control flow-based testing includes cases that may not be identified from specifications alone.
  – Typical case: Implementation of a single item of the specification by multiple parts of the program
  – E.g. Hash table collision (invisible in interface specification)

• Test suites that satisfy control flow adequacy criteria could fail in revealing faults that can be caught with functional criteria.
  – Typical case: Missing path faults
Structural Testing, in Practice

• Create functional test suite first, then measure structural coverage to identify and see what is missing.

• Interpret unexecuted elements
  – May be due to natural differences between specification and implementation
  – May reveal flaws of the software or its development process
    • Inadequacy of specifications that do not include cases present in the implementation
    • Coding practice that radically diverges from the specification
    • Inadequate functional test suites

• Attractive because structural testing is automated
  – Coverage measurements are convenient progress indicators.
  – Sometimes used as a criterion of completion of testing
    • Use with caution: does not ensure effective test suites
An Example Program: ‘cgi_decode’ and CFG

```c
#include "hex_values.h"

int cgi_decode(char* encoded, char* *decoded) {
    char *eptr = encoded;
    char *dptr = decoded;
    int ok = 0;

    while (*eptr) {
        char c;
        c = *eptr;
        if (c == '+') {
            *dptr = ' ';  
        } else if (c == '%') {
            int digit_high = Hex_Values[*(++eptr)];
            int digit_low = Hex_Values[*(++eptr)];
            if (digit_high == -1 || digit_low == -1) {
                ok = 1;
            } else {
                *dptr = 16 * digit_high + digit_low;
            }
        } else {
            *dptr = *eptr;
        }
        ++dptr;
        ++eptr;
    }
    *dptr = '\0';
    return ok;
}
```
Structural Testing Techniques

1. Statement Testing

2. Branch Testing

3. Condition Testing
   - Basic
   - Compounded
   - MC/DC

4. Path Testing
   - Bounded interior
   - Loop boundary
   - LCSAJ
   - Cyclomatic
1. Statement Testing

• Adequacy criterion:
  – Each statement (or node in the CFG) must be executed at least once.

• Coverage:
  \[
  \text{number of executed statements} / \text{number of statements}
  \]

• Rationale:
  – A fault in a statement can only be revealed by executing the faulty statement.

• Nodes in a CFG often represent basic blocks of multiple statements.
  – Some standards refer to ‘basic block coverage’ or ‘node coverage’.
  – Difference in granularity, but not in concept
An Example: for Function “cgi_decode”

```
< Test cases >
T₀ = {'"", "test", "test+case%1Dadequacy"'}
17/18 = 94% Statement coverage

T₁ = {'"adequate+test%0Dexec%7U"'}
18/18 = 100% Statement coverage

T₂ = {'"%3D", "%A", "a+b", "test"'}
18/18 = 100% Statement coverage

T₃ = {'"", "+%0D+%4J"'}
...

T₄ = {'"first+test%9Ktest%K9"'}
...
Coverage is not a Matter of Size

• Coverage does not depend on the number of test cases.
  - $T_0, T_1: T_1 >_{\text{coverage}} T_0 \quad T_1 <_{\text{cardinality}} T_0$
  - $T_1, T_2: T_2 =_{\text{coverage}} T_1 \quad T_2 >_{\text{cardinality}} T_1$

• Minimizing test suite size is not the goal.
  - Small test cases make failure diagnosis easier.
  - But, a failing test case in $T_2$ gives more information for fault localization than a failing test case in $T_1$
Complete Statement Coverage

- Complete statement coverage may not imply executing all branches in a program.

- Example:
  - Suppose block F were missing
  - But, statement adequacy would not require false branch from D to L

- T3 = {"", "+%0D+%4J"}
  - 100% statement coverage
  - No false branch from D
2. Branch Testing

• Adequacy criterion:
  – Each branch (edge in the CFG) must be executed at least once.

• Coverage:

\[
\frac{\text{number of executed branches}}{\text{number of branches}}
\]

• Example:
  – \( T_3 = \{"", "+%0D+%4J"\} \)
    • 100% Stmt Cov.
    • 88% Branch Cov. (7/8 branches)
  – \( T_2 = \{"%3D", "%A", "a+b", "test"\} \)
    • 100% Stmt Cov.
    • 100% Branch Cov. (8/8 branches)
Statements vs. Branches

- Traversing all edges causes all nodes to be visited.
  - Therefore, test suites that satisfy the branch adequacy also satisfy the statement adequacy criterion for the same program.
  - Branch adequacy subsumes statement adequacy.

- The converse is not true (see T₃)
  - A statement-adequate test suite may not be branch-adequate.
All Branches Coverage

• “All branches coverage” can still miss conditions.

• Example:
  – Supposed that we missed the negation operator of “digit_high == -1”
    \[\text{digit_high} == 1 \text{ || digit_low} == -1\]

• Branch adequacy criterion can be satisfied by varying only ‘digit_low’.
  – The faulty sub-expression might never determine the result.
  – We might never really test the faulty condition, even though we tested both outcomes of the branch.
3. Condition Testing

- **Branch coverage** exposes faults in how a computation has been decomposed into cases.
  - Intuitively attractive: checking the programmer’s case analysis
  - But, only roughly: grouping cases with the same outcome

- **Condition coverage** considers case analysis in more detail.
  - Consider ‘individual conditions’ in a compound Boolean expression
    - E.g. both parts of “\( \text{digit}_{\text{high}} == 1 \lor \text{digit}_{\text{low}} == -1 \)"

- **Adequacy criterion:**
  - Each basic condition must be executed at least once.

- **Basic condition testing coverage:**
  \[
  \text{number of truth values taken by all basic conditions} = 2 \times \text{number of basic conditions}
  \]
Basic Conditions vs. Branches

• Basic condition adequacy criterion can be satisfied without satisfying branch coverage.

• T4 = {“first+test%9Ktest%K9”}
  – Satisfies basic condition adequacy
  – But, does not satisfy branch condition adequacy

• Branch and basic condition are not comparable.
  – Neither implies the other.
Covering Branches and Conditions

- Branch and condition adequacy:
  - Cover all conditions and all decisions

- Compound condition adequacy:
  - Cover all possible evaluations of compound conditions.
  - Cover all branches of a decision tree.
Compounded Conditions

- Compound conditions often have exponential complexity.

- Example: (((a || b) && c) || d) && e

<table>
<thead>
<tr>
<th>Test Case</th>
<th>a</th>
<th>b</th>
<th>c</th>
<th>d</th>
<th>e</th>
</tr>
</thead>
<tbody>
<tr>
<td>(1)</td>
<td>T</td>
<td></td>
<td>T</td>
<td></td>
<td>T</td>
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<tr>
<td>(2)</td>
<td>F</td>
<td>T</td>
<td>T</td>
<td></td>
<td>T</td>
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<td>(3)</td>
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</tr>
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<td>F</td>
<td>T</td>
<td>F</td>
<td>F</td>
<td></td>
</tr>
<tr>
<td>(13)</td>
<td>F</td>
<td>F</td>
<td></td>
<td>F</td>
<td></td>
</tr>
</tbody>
</table>
Modified Condition/Decision (MC/DC)

• Motivation
  – Effectively test important combinations of conditions, without exponential blowup in test suite size
  – “Important” combinations means:
    • Each basic condition shown to independently affect the outcome of each decision

• Requires
  – For each basic condition C, two test cases,
  – Values of all ‘evaluated’ conditions except C are the same.
  – Compound condition as a whole evaluates to ‘true’ for one and ‘false’ for the other.
Complexity of MC/DC

• MC/DC has a linear complexity.

• Example: (((a || b) && c) || d) && e

<table>
<thead>
<tr>
<th>Test Case</th>
<th>a</th>
<th>b</th>
<th>c</th>
<th>d</th>
<th>e</th>
<th>outcome</th>
</tr>
</thead>
<tbody>
<tr>
<td>(1)</td>
<td>true</td>
<td>--</td>
<td>true</td>
<td>--</td>
<td>true</td>
<td>true</td>
</tr>
<tr>
<td>(2)</td>
<td>false</td>
<td>true</td>
<td>true</td>
<td>--</td>
<td>true</td>
<td>true</td>
</tr>
<tr>
<td>(3)</td>
<td>true</td>
<td>--</td>
<td>false</td>
<td>true</td>
<td>true</td>
<td>true</td>
</tr>
<tr>
<td>(6)</td>
<td>true</td>
<td>--</td>
<td>true</td>
<td>--</td>
<td>false</td>
<td>false</td>
</tr>
<tr>
<td>(11)</td>
<td>true</td>
<td>--</td>
<td>false</td>
<td>false</td>
<td>--</td>
<td>false</td>
</tr>
<tr>
<td>(13)</td>
<td>false</td>
<td>false</td>
<td>--</td>
<td>false</td>
<td>--</td>
<td>false</td>
</tr>
</tbody>
</table>

• Underlined values independently affect the output of the decision.
  – Required by the RTCA/DO-178B standard
Comments on MC/DC

• MC/DC is
  – Basic condition coverage (C)
  – Branch coverage (DC)
  – Plus one additional condition (M)
    • Every condition must independently affect the decision’s output.

• It is subsumed by compound conditions and subsumes all other criteria discussed so far.
  – Stronger than statement and branch coverage

• A good balance of thoroughness and test size
  – Widely used
4. Path Testing

- There are many more paths than branches.
  - Decision and condition adequacy criteria consider individual decisions only.

- Path testing focuses combinations of decisions along paths.

- Adequacy criterion:
  - Each path must be executed at least once.

- Coverage:
  \[
  \text{number of executed paths} \quad \frac{\text{number of executed paths}}{\text{number of paths}}
  \]
Path Coverage Criteria in Practice

• The number of paths in a program with loops is unbounded.
  – Usually impossible to satisfy

• For a feasible criterion,
  – Should partition infinite set of paths into a finite number of classes

• Useful criteria can be obtained by limiting
  – Number of traversals of loops
  – Length of the paths to be traversed
  – Dependencies among selected paths
Boundary Interior Path Testing

- Group together paths that differ only in the subpath they follow, when repeating the body of a loop
  - Follow each path in the CFG up to the first repeated node
  - The set of paths from the root of the tree to each leaf is the required set of subpaths for boundary interior coverage.

Paths derived from the CFG

Paths for boundary interior path testing
Limitations of Boundary Interior Adequacy

• The number of paths can still grow exponentially

```python
if (a) { S₁; }
if (b) { S₂; }
if (c) { S₃; }
...
if (x) { Sₙ; }
```

• The subpaths through this control flow can include or exclude each of the statements $S_i$, so that in total $N$ branches result in $2^N$ paths that must be traversed.

• Choosing input data to force execution of one particular path may be very difficult, or even impossible if the conditions are not independent.
Loop Boundary Adequacy

- Variant of the boundary/interior criterion
  - Treats loop boundaries similarly, but is less stringent with respect to other differences among paths.

- Criterion:
  - A test suite satisfies the loop boundary adequacy criterion iff, for every loop:
    - In at least one test case, the loop body is iterated zero times.
    - In at least one test case, the loop body is iterated once.
    - In at least one test case, the loop body is iterated more than once.

- Corresponds to the cases that would be considered in a formal correctness proof for the loop
LCSAJ Adequacy

• Linear Code Sequence And Jumps (LCSAJ)
  – Sequential subpath in the CFG starting and ending in a branch
    • $\text{TER}_1$ = statement coverage
    • $\text{TER}_2$ = branch coverage
    • $\text{TER}_{n+2}$ = coverage of $n$ consecutive LCSAJs
  – Essentially considering full path coverage of (short) sequences of decisions

• Data flow criteria considered in a later chapter provide a more principled way of choosing some particular sub-paths as important enough to cover in testing.
  – But, neither LCSAJ nor data flow criteria are much used in current practice.
Cyclomatic Adequacy

• **Cyclomatic number**
  – Number of independent paths in the CFG
  – A path is representable as a bit vector, where each component of the vector represents an edge.
  – “Dependence” is ordinary linear dependence between (bit) vectors

• If \( e = \#\text{edges}, n = \#\text{nodes}, c = \#\text{connected components of a graph} \),
  – \( e - n + c \) for an arbitrary graph
  – \( e - n + 2 \) for a CFG \( \leftarrow \) Cyclomatic complexity

• **Cyclomatic coverage** counts the number of independent paths that have been exercised, relative to cyclomatic complexity.
Procedure Call Testing

- Measure coverage of control flow within individual procedures.
  - Not well suited to integration or system testing

- Choose a coverage granularity commensurate with the granularity of testing
  - If unit testing has been effective, then faults that remain to be found in integration testing will be primarily interface faults, and testing effort should focus on interfaces between units rather than their internal details.

- Procedure entry and exit testing
  - Procedure may have multiple entry points (e.g., Fortran) and multiple exit points.

- Call coverage
  - The same entry point may be called from many points.
Comparing Structural Testing Criteria

Subsumption Relation among Structural Test Adequacy Criteria
The Infeasibility Problem

- Sometimes criteria may not be satisfiable.
  - The criterion requires execution of
    - Statements that cannot be executed as a result of
      - Defensive programming
      - Code reuse (reusing code that is more general than strictly required for the application)
    - Conditions that cannot be satisfied as a result of
      - Interdependent conditions
    - Paths that cannot be executed as a result of
      - Interdependent decisions
Satisfying Structural Criteria

• Large amounts of ‘fossil’ code may indicate serious maintainability problems.
• But, some unreachable code is common even in well-designed and well-maintained systems.

• Solutions:
  1. Make allowances by setting a coverage goal less than 100%
  2. Require justification of elements left uncovered
     • As RTCA-DO-178B and EUROCAE ED-12B for modified MC/DC
Summary

- We defined a number of adequacy criteria.
  - NOT test design techniques
  - Different criteria address different classes of errors.

- Full coverage is usually unattainable.
  - Attainability is an undecidable problem.

- Rather than requiring full adequacy, the “degree of adequacy” of a test suite is estimated by coverage measures.
Chapter 13.
Data Flow Testing
Learning Objectives

• Understand why data flow criteria have been designed and used
• Recognize and distinguish basic DF criteria
  – All DU pairs, all DU paths, all definitions

• Understand how the infeasibility problem impacts data flow testing
• Appreciate limits and potential practical uses of data flow testing
Motivation

• Middle ground in structural testing
  – Node and edge coverage don’t test interactions.
  – Path-based criteria require impractical number of test cases.
    • Only a few paths uncover additional faults, anyway.
  – Need to distinguish “important” paths

• Intuition: Statements interact through data flow.
  – Value computed in one statement, is used in another.
  – Bad value computation can be revealed only when it is used.
Def-Use Pairs

- Value of x at 6 could be computed at 1 or at 4.
- Bad computation at 1 or 4 could be revealed only if they are used at 6.
- (1, 6) and (4, 6) are def-use (DU) pairs.
  - defs at 1, 4
  - use at 6
Terminology

- **DU pair**
  - A pair of definition and use for some variable, such that at least one DU path exists from the definition to the use.
  - “\(x = \ldots\)” is a definition of \(x\)
  - “\(= \ldots x \ldots\)” is a use of \(x\)

- **DU path**
  - A definition-clear path on the CFG starting from a definition to a use of a same variable
  - Definition clear: Value is not replaced on path.
  - Note: Loops could create infinite DU paths between a def and a use.
Definition-Clear Path

• 1,2,3,5,6 is a definition-clear path from 1 to 6.
  – x is not re-assigned between 1 and 6.

• 1,2,4,5,6 is not a definition-clear path from 1 to 6.
  – the value of x is “killed” (reassigned) at node 4.

• (1, 6) is a DU pair because 1,2,3,5,6 is a definition-clear path.
Adequacy Criteria

- All DU pairs
  - Each DU pair is exercised by at least one test case.

- All DU paths
  - Each simple (non looping) DU path is exercised by at least one test case.

- All definitions
  - For each definition, there is at least one test case which exercises a DU pair containing it.
    - Because, every computed value is used somewhere.

- Corresponding coverage fractions can be defined similarly.
Difficult Cases

• \( x[i] = \ldots ; \ldots ; y = x[j] \)
  – DU pair (only) if \( i=\neq j \)

• \( p = \&x ; \ldots ; *p = 99 ; \ldots ; q = x \)
  – \( *p \) is an alias of \( x \)

• \( m\text{.putFoo}(\ldots); \ldots ; y=n\text{.getFoo}(\ldots); \)
  – Are \( m \) and \( n \) the same object?
  – Do \( m \) and \( n \) share a “foo” field?

• Problem of aliases:
  – Which references are (always or sometimes) the same?
Data Flow Coverage with Complex Structures

• Arrays and pointers are critical for data flow analysis.
  – Under-estimation of aliases may fail to include some DU pairs.
  – Over-estimation may introduce unfeasible test obligations.

• For testing, it may be preferable to accept under-estimation of alias set rather than over-estimation or expensive analysis.
  – Alias analysis may rely on external guidance or other global analysis to calculate good estimates.
  – Undisciplined use of dynamic storage, pointer arithmetic, etc. may make the whole analysis infeasible.
  – But, in other applications (e.g., compilers), a conservative over-estimation of aliases is usually required.
The Infeasibility Problem

Why? – I don’t Know!

• Suppose 'cond' has not changed between 1 and 5.
  – Or the conditions could be different, but the first implies the second.

• Then (3,5) is not a (feasible) DU pair.
  – But it is difficult or impossible to determine which pairs are infeasible.

• Infeasible test obligations are a problem.
  – No test case can cover them.
Data Flow Coverage in Practice

- The path-oriented nature of data flow analysis makes the infeasibility problem especially relevant.
  - Combinations of elements matter.
  - Impossible to (infallibly) distinguish feasible from infeasible paths.
  - More paths = More work to check manually.

- In practice, reasonable coverage is (often, not always) achievable.
  - Number of paths is exponential in worst case, but often linear.
  - All DU paths is more often impractical.
Summary

• Data flow testing attempts to distinguish “important” paths: Interactions between statements.
  – Intermediate between simple statement and branch coverage and more expensive path-based structural testing

• Cover Def-Use (DU) pairs: From computation of value to its use
  – Intuition: Bad computed value is revealed only when it is used.
  – Levels: All DU pairs, all DU paths, all defs (some use)

• Limits: Aliases, infeasible paths
  – Worst case is bad (undecidable properties, exponential blowup of paths), so pragmatic compromises are required.
Chapter 14.
Model-Based Testing
Learning Objectives

• Understand the role of models in devising test cases
  – Principles underlying functional and structural test adequacy criteria, as well as model-based testing

• Understand some examples of model-based testing techniques
• Be able to understand, devise and refine other model-based testing techniques
Identify Independently Testable Features

- Functional Specifications
- Independently Testable Feature
  - Derive a Model
  - Infinite State Machine
  - Grammar
  - Algebraic Specification
  - Logic Specification
  - Control/Data Flow Graph

Representative Values
- Generate Test-Case Specifications
  - Semantic Constraints
  - Combinatorial Selection
  - Exhaustive Enumeration
  - Random Selection

Model
- Generate Test-Case Specifications
  - Test Selection Criteria

Test Case Specifications
- Generate Test Cases
  - Manual Mapping
  - Symbolic Execution
  - A-posteriori Satisfaction

Test Cases
- Instantiate Tests

Scaffolding
Overview

- Models used in specification or design have structure.
  - Useful information for selecting representative classes of behavior
  - Behaviors that are treated differently with respect to the model should be tried by a thorough test suite.
  - In combinatorial testing, it is difficult to capture that structure clearly and correctly in constraints.

- **We can devise test cases to check actual behavior against behavior specified by the model.**
  - “Coverage” similar to structural testing, but applied to specification and design models
Deriving Test Cases from Finite State Machines

Informal Specification → FSM → Test Cases
Informal Specification: Feature “Maintenance” of the Chipmunk Web Site

**Maintenance**: The Maintenance function records the history of items undergoing maintenance.

If the product is covered by warranty or maintenance contract, maintenance can be requested either by calling the maintenance toll free number, or through the web site, or by bringing the item to a designated maintenance station.

If the maintenance is requested by phone or web site and the customer is a US or EU resident, the item is picked up at the customer site, otherwise, the customer shall ship the item with an express courier.

If the maintenance contract number provided by the customer is not valid, the item follows the procedure for items not covered by warranty.

If the product is not covered by warranty or maintenance contract, maintenance can be requested only by bringing the item to a maintenance station. The maintenance station informs the customer of the estimated costs for repair. Maintenance starts only when the customer accepts the estimate.

If the customer does not accept the estimate, the product is returned to the customer.

Small problems can be repaired directly at the maintenance station. If the maintenance station cannot solve the problem, the product is sent to the maintenance regional headquarters (if in US or EU) or to the maintenance main headquarters (otherwise).

If the maintenance regional headquarters cannot solve the problem, the product is sent to the maintenance main headquarters.

Maintenance is suspended if some components are not available.

Once repaired, the product is returned to the customer.
Corresponding Finite State Machine

1. **Wait for returning**
2. **Maintenance (no warranty)**
3. **Wait for pick up**
4. **Wait for acceptance**
5. **Repair (maintenance station)**
6. **Repair (main headquarters)**
7. **Wait for component**
8. **Repair (regional headquarters)**

- **NO Maintenance**
  - Request at maintenance station (no warranty)
  - Request by phone or web (contract number)
  - Request at maintenance station or by express courier (contract number)

- **Repair completed**

- **Repair (US or EU resident)**
  - Component arrives (a)
  - Unable to repair (US or EU resident)

- **Repair (not US or EU resident)**
  - Component arrives (b)
  - Unable to repair

- **Repair (component arrives (c))**

- **Repair (component arrives (b))**

- **Repair (component arrives (a))**
Test Cases Generated from the FSM

- FSM can be used both to
  1. Guide test selection (checking each state transition)
  2. Constructing an oracle that judge whether each observed behavior is correct

<table>
<thead>
<tr>
<th>TC1</th>
<th>0</th>
<th>2</th>
<th>4</th>
<th>1</th>
<th>0</th>
</tr>
</thead>
<tbody>
<tr>
<td>TC2</td>
<td>0</td>
<td>5</td>
<td>2</td>
<td>4</td>
<td>5</td>
</tr>
<tr>
<td>TC3</td>
<td>0</td>
<td>3</td>
<td>5</td>
<td>9</td>
<td>6</td>
</tr>
<tr>
<td>TC4</td>
<td>0</td>
<td>3</td>
<td>5</td>
<td>7</td>
<td>5</td>
</tr>
</tbody>
</table>

- Questions:
  - Is this a thorough test suite?
  - How can we judge?
    → Coverage criteria require.
Transition Coverage Criteria

- **State coverage**
  - Every state in the model should be visited by at least one test case.

- **Transition coverage**
  - Every transition between states should be traversed by at least one test case.
  - Most commonly used criterion
  - A transition can be thought of as a (precondition, postcondition) pair
Path Sensitive Criteria

• Basic assumption: States fully summarize history.
  – No distinction based on how we reached a state
  – But, this should be true of well-designed state machine models.

• If the assumption is violated, we may distinguish paths and devise criteria to cover them
  – Single state path coverage:
    • Traverse each subpath that reaches each state at most once
  – Single transition path coverage:
    • Traverse each subpath that reaches each transition at most once
  – Boundary interior loop coverage:
    • Each distinct loop of the state machine must be exercised the minimum, an intermediate, and the maximum or a large number of times
    • Of the path sensitive criteria, only boundary-interior is common.
Deriving Test Cases from Decision Structures

- Some specifications are structured as decision tables, decision trees, or flow charts.
- We can exercise these as if they were program source code.
Informal Specification: Feature “Price” of the Chipmunk Web Site

**Pricing:** The pricing function determines the adjusted price of a configuration for a particular customer.

The scheduled price of a configuration is the sum of the scheduled price of the model and the scheduled price of each component in the configuration. The adjusted price is either the scheduled price, if no discounts are applicable, or the scheduled price less any applicable discounts.

There are three price schedules and three corresponding discount schedules, Business, Educational, and Individual.

....

Educational prices: The adjusted price for a purchase charged to an educational account in good standing is the scheduled price from the educational price schedule. No further discounts apply.

...

Special-price non-discountable offers: Sometimes a complete configuration is offered at a special, non-discountable price. When a special, non-discountable price is available for a configuration, the adjusted price is the non-discountable price or the regular price after any applicable discounts, whichever is less.
### Corresponding Decision Table

<table>
<thead>
<tr>
<th></th>
<th>Education</th>
<th>Individual</th>
</tr>
</thead>
<tbody>
<tr>
<td>EduAc</td>
<td>T</td>
<td>T</td>
</tr>
<tr>
<td>BusAc</td>
<td>-</td>
<td></td>
</tr>
<tr>
<td>CP &gt; CT1</td>
<td>-</td>
<td>F</td>
</tr>
<tr>
<td>YP &gt; YT1</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>CP &gt; CT2</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>YP &gt; YT2</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>SP &lt; Sc</td>
<td>F</td>
<td>T</td>
</tr>
<tr>
<td>SP &lt; T1</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>SP &lt; T2</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Out</td>
<td>Edu</td>
<td>SP</td>
</tr>
</tbody>
</table>

**Constraints**

- at-most-one (EduAc, BusAc)
- YP > YT2 → YP > YT1
- CP > CT2 → CP > CT1
- SP > T2 → SP > T1
- at-most-one (YP < YT1, YP > YT2)
- at-most-one (CP < CT1, CP > CT2)
- at-most-one (SP < T1, SP > T2)
Test Cases Generated from the Decision Table

- Basic condition coverage
  - A test case specification for each column in the table

- Compound condition adequacy criterion
  - A test case specification for each combination of truth values of basic conditions

- Modified condition/decision adequacy criterion (MC/DC)
  - Each column in the table represents a test case specification.
  - We add columns that differ in one input row and in outcome, then merge compatible columns.
A Part of Test Cases by Applying MC/DC

<table>
<thead>
<tr>
<th></th>
<th>C.1</th>
<th>C.1a</th>
<th>C.1b</th>
<th>C.10</th>
</tr>
</thead>
<tbody>
<tr>
<td>EduAc</td>
<td>T</td>
<td>F</td>
<td>T</td>
<td>-</td>
</tr>
<tr>
<td>BusAc</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>T</td>
</tr>
<tr>
<td>CP &gt; CT1</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>F</td>
</tr>
<tr>
<td>YP &gt; YT1</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>F</td>
</tr>
<tr>
<td>CP &gt; CT2</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>YP &gt; YT2</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>SP &gt; Sc</td>
<td>F</td>
<td>F</td>
<td>T</td>
<td>T</td>
</tr>
<tr>
<td>SP &gt; T1</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>SP &gt; T2</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Out</td>
<td>Edu</td>
<td>*</td>
<td>*</td>
<td>SP</td>
</tr>
</tbody>
</table>

Generate C.1a and C.1b by flipping one element of C.1.

C.1b can be merged with an existing column (C.10) in the specification. (?)

Outcome of generated columns must differ from source column.
Deriving Test Cases from Control and Data Flow Graph

• If the specification or model has both decisions and sequential logic, we can cover it like program source code.

• Flowgraph based testing
Informal Specification: Feature “Process Shipping Order” of the Chipmunk Web Site

**Process shipping order**: The Process shipping order function checks the validity of orders and prepares the receipt.

A valid order contains the following data:

- cost of goods: If the cost of goods is less than the minimum processable order (MinOrder) then the order is invalid.
- shipping address: The address includes name, address, city, postal code, and country.
- preferred shipping method: If the address is domestic, the shipping method must be either land freight, expedited land freight, or overnight air; If the address is international, the shipping method must be either air freight, or expedited air freight.
- type of customer which can be individual, business, educational
- preferred method of payment. Individual customers can use only credit cards, business and educational customers can choose between credit card and invoice.
- card information: if the method of payment is credit card, fields credit card number, name on card, expiration date, and billing address, if different than shipping address, must be provided. If credit card information is not valid the user can either provide new data or abort the order.

The outputs of Process shipping order are

- validity: Validity is a boolean output which indicates whether the order can be processed.
- total charge: The total charge is the sum of the value of goods and the computed shipping costs (only if validity = true).
- payment status: if all data are processed correctly and the credit card information is valid or the payment is invoice, payment status is set to valid, the order is entered and a receipt is prepared; otherwise validity = false.
Corresponding Control Flow Graph

Process shipping order

CostOfGoods < MinOrder

international shipping address domestic

preferred shipping method = air freight OR expedited air freight

preferred shipping method = land freight, OR expedited land freight OR overnight air

calculate international shipping charge
calculate domestic shipping charge

total charge = goods + shipping

individual customer

no

method of payment

yes

credit card

no

invoice

yes

obtain credit card data: number, name on card, expiration date

billing address = shipping address

valid credit card information

no

no

obtain billing address

valid credit card information

yes

enter order

prepare receipt

payment status = valid

no

no

abort order?

yes

no

invalid order
Test Cases Generated from the CFG

- **Node adequacy criteria**

<table>
<thead>
<tr>
<th>Case</th>
<th>Too Small</th>
<th>Ship Where</th>
<th>Ship Method</th>
<th>Cust Type</th>
<th>Pay Method</th>
<th>Same Address</th>
<th>CC valid</th>
</tr>
</thead>
<tbody>
<tr>
<td>TC-1</td>
<td>No</td>
<td>Int</td>
<td>Air</td>
<td>Bus</td>
<td>CC</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>TC-2</td>
<td>No</td>
<td>Dom</td>
<td>Air</td>
<td>Ind</td>
<td>CC</td>
<td>-</td>
<td>No (abort)</td>
</tr>
</tbody>
</table>

- **Branch adequacy criteria**

<table>
<thead>
<tr>
<th>Case</th>
<th>Too Small</th>
<th>Ship Where</th>
<th>Ship Method</th>
<th>Cust Type</th>
<th>Pay Method</th>
<th>Same Address</th>
<th>CC valid</th>
</tr>
</thead>
<tbody>
<tr>
<td>TC-1</td>
<td>No</td>
<td>Int</td>
<td>Air</td>
<td>Bus</td>
<td>CC</td>
<td>No</td>
<td>Yes</td>
</tr>
<tr>
<td>TC-2</td>
<td>No</td>
<td>Dom</td>
<td>Land</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>TC-3</td>
<td>Yes</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>TC-4</td>
<td>No</td>
<td>Dom</td>
<td>Air</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>TC-5</td>
<td>No</td>
<td>Int</td>
<td>Land</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>TC-6</td>
<td>No</td>
<td>-</td>
<td>Edu</td>
<td>Inv</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>TC-7</td>
<td>No</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>CC</td>
<td>Yes</td>
<td>-</td>
</tr>
<tr>
<td>TC-8</td>
<td>No</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>CC</td>
<td>-</td>
<td>No (abort)</td>
</tr>
<tr>
<td>TC-9</td>
<td>No</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>CC</td>
<td>-</td>
<td>No (no abort)</td>
</tr>
</tbody>
</table>
Deriving Test Cases from Grammars

- Grammars are good at:
  - Representing inputs of varying and unbounded size
  - With recursive structure and boundary conditions

- Examples:
  - Complex textual inputs
  - Trees (search trees, parse trees, ...)
    - Example: XML and HTML are trees in textual form
  - Program structures
    - Which are also tree structures in textual format
Grammar-Based Testing

- Test cases are ‘strings’ generated from the grammar

- Coverage criteria:
  - Production coverage:
    - Each production must be used to generate at least one (section of) test case.
  - Boundary condition:
    - Annotate each recursive production with minimum and maximum number of application, then generate:
      - Minimum
      - Minimum + 1
      - Maximum - 1
      - Maximum
Informal Specification: Feature “Check Configuration” of the Chipmunk Web Site

**Check configuration:** The Check-configuration function checks the validity of a computer configuration.

Model: A model identifies a specific product and determines a set of constraints on available components. Models are characterized by logical slots for components, which may or may not be implemented by physical slots on a bus. Slots may be required or optional. Required slots must be assigned with a suitable component to obtain a legal configuration, while optional slots may be left empty or filled depending on the customers’ needs.

Example: The required “slots” of the Chipmunk C20 laptop computer include a screen, a processor, a hard disk, memory, and an operating system. (Of these, only the hard disk and memory are implemented using actual hardware slots on a bus.) The optional slots include external storage devices such as a CD/DVD writer.

Set of Components: A set of [slot,component] pairs, which must correspond to the required and optional slots associated with the model. A component is a choice that can be varied within a model, and which is not designed to be replaced by the end user. Available components and a default for each slot is determined by the model. The special value empty is allowed (and may be the default selection) for optional slots. In addition to being compatible or incompatible with a particular model and slot, individual components may be compatible or incompatible with each other.

Example: The default configuration of the Chipmunk C20 includes 20 gigabytes of hard disk; 30 and 40 gigabyte disks are also available. (Since the hard disk is a required slot, empty is not an allowed choice.) The default operating system is RodentOS 3.2, personal edition, but RodentOS 3.2 mobile server edition may also be selected. The mobile server edition requires at least 30 gigabytes of hard disk.

※ It is not the example in the text.
Corresponding Grammar with Limits

Model

```
<Model> ::= <modelNumber> <compSequence> 
   <optCompSequence>
```

```
compSeq1 [0, 16] <compSequence> ::= <Component> <compSequence>
```

```
compSeq2 <compSequence> ::= empty
```

```
optCompSeq1 [0, 16] <optCompSequence> ::= <OptionalComponent> <optCompSequence>
```

```
optCompSeq2 <optCompSequence> ::= empty
```

```
Comp <Component> ::= <ComponentType> <ComponentValue>
```

```
OptComp <OptionalComponent> ::= <ComponentType>
```

```
modNum <modelNumber> ::= string
```

```
CompTyp <ComponentType> ::= string
```

```
CompVal <ComponentValue> ::= string
```
Test Cases Generated from the Grammar

- “Mod000”
  - Covers Model, compSeq1[0], compSeq2, optCompSeq1[0], optCompSeq2, modNum

- “Mod000 (Comp000, Val000) (OptComp000)”
  - Covers Model, compSeq1[1], compSeq2, optCompSeq2[0], optCompSeq2, Comp, OptComp, modNum, CompTyp, CompVal

- Etc.

- Comments:
  - By first applying productions with nonterminals on the right side, we obtain few, large test cases.
  - By first applying productions with terminals on the right side, we obtain many, small test cases.
Grammar Testing vs. Combinatorial Testing

- Combinatorial specification-based testing is good for “mostly independent” parameters.
  - We can incorporate a few constraints, but complex constraints are hard to represent and use.
  - We must often “factor and flatten.”
  - E.g. separate “set of slots” into characteristics “number of slots” and predicates about what is in the slots (all together)

- Grammar describes sequences and nested structure naturally.
  - But, some relations among different parts may be difficult to describe and exercise systematically, e.g. compatibility of components with slots.
Summary

• Models are useful abstractions.
  – In specification and design, they help us think and communicate about complex artifacts by emphasizing key features and suppressing details.
  – Models convey structure and help us focus on one thing at a time.

• We can use them in systematic testing.
  – If a model divides behavior into classes, we probably want to exercise each of those classes.
  – Common model-based testing techniques are based on state machines, decision structures, and grammars.
  – But, we can apply the same approach to other models.
Chapter 15.
Testing Object-Oriented Software
Chapter 16.
Fault-Based Testing
Learning Objectives

• Understand the basic ideas of fault-based testing
  – How knowledge of a fault model can be used to create useful tests and judge the quality of test cases
  – Understand the rationale of fault-based testing well enough to distinguish between valid and invalid uses

• Understand mutation testing as one application of fault-based testing principles
Estimating Test Suite Quality

• Supposed that I have a program with bugs.

• Add 100 new bugs
  – Assume they are exactly like real bugs in every way
  – I make 100 copies of my program, each with one of my 100 new bugs.

• Run my test suite on the programs with seeded bugs
  – And the tests revealed 20 of the bugs.
  – The other 80 program copies do not fail.

• What can I infer about my test suite’s quality?
Basic Assumptions

- We want to judge effectiveness of a test suite in finding real faults, 
  - by measuring how well it finds seeded fake faults.

- Valid to the extent that the seeded bugs are representative of real bugs 
  - Not necessarily identical 
  - But, the differences should not affect the selection
Mutation Testing

- A **mutant** is a copy of a program with a mutation.

- A **mutation** is a syntactic change (a seeded bug).
  - Example: change \((i < 0)\) to \((i <= 0)\)

- Run test suite on all the mutant programs

- A mutant is **killed**, if it fails on at least one test case. (The bug is found.)

- If many mutants are killed, infer that the test suite is also effective at finding real bugs.
Assumptions on Mutation Testing

• Competent programmer hypothesis
  – Programs are nearly correct.
    • Real faults are small variations from the correct program.
    • Therefore, mutants are reasonable models of real buggy programs.

• Coupling effect hypothesis
  – Tests that find simple faults also find more complex faults.
  – Even if mutants are not perfect representatives of real faults, a test suite that kills mutants is good at finding real faults too.
Mutant Operators

• Syntactic changes from legal program to illegal program
  – Specific to each programming language

• Examples:
  – crp: constant for constant replacement
    • E.g. from $(x < 5)$ to $(x < 12)$
    • Select constants found somewhere in program text
  – ror: relational operator replacement
    • E.g. from $(x <= 5)$ to $(x < 5)$
  – vie: variable initialization elimination
    • E.g. change `int x =5;` to `int x;`
Fault-based Adequacy Criteria

• Mutation analysis consists of the following steps:
  1. Select mutation operators
  2. Generate mutants
  3. Distinguish mutants

• Live mutants
  – Mutants not killed by a test suite

• Given a set of mutants SM and a test suite T, the fraction of nonequivalence mutants killed by T measures the adequacy of T with respect to SM.
Variations on Mutation Analysis

• Problem:
  – There are lots of mutants.
  – Running each test case to completion on every mutant is expensive.
  – Number of mutants grows with the square of program size.

• Solutions:
  – Weak mutation:
    • Execute meta-mutant (with many seeded faults) together with original program
  – Statistical mutation
    • Just create a random sample of mutants
Summary

• Fault-based testing is a widely used in semiconductor manufacturing.
  – With good fault models of typical manufacturing faults, e.g. “stuck-at-one” for a transistor
  – But, fault-based testing for design errors is more challenging (as in software).

• Mutation testing is not widely used in industry.
  – But, plays a role in software testing research, to compare effectiveness of testing techniques
Chapter 17.
Test Execution
Learning Objectives

• Appreciate the purpose of test automation
  – Factoring repetitive and mechanical tasks from creative and human design tasks in testing

• Recognize main kinds and components of test scaffolding

• Understand some key dimensions in test automation design
  – Design for testability: Controllability and observability
  – Degrees of generality in drivers and stubs
  – Comparison-based oracles and self-checks
Automating Test Execution

- Designing test cases and test suites is creative.
  - Demanding intellectual activity
  - Requiring human judgment

- Executing test cases should be automatic.
  - Design once, execute many times

- Test automation separates the creative human process from the mechanical process of test execution.
From Test Case Specifications to Test Cases

- Test design often yields test case specifications, rather than concrete data.
  - E.g. “a large positive number”, not 420,023
  - E.g. “a sorted sequence, length > 2”, not “Alpha, Beta, Chi, Omega”
- Other details for execution may be omitted.

- **Test Generation** creates concrete, executable test cases from test case specifications.

- A **Tool chain** for test case generation & execution
  - A combinatorial test case generation to create test data
    - Optional: Constraint-based data generator to “concretize” individual values, e.g., from “positive integer” to 42
  - ‘DDSteps’ to convert from spreadsheet data to ‘JUnit’ test cases
  - ‘JUnit’ to execute concrete test cases
Scaffolding

• Code produced to support development activities
  – Not part of the “product” as seen by the end user
  – May be temporary (like scaffolding in construction of buildings)

• Scaffolding includes
  – Test harnesses
  – Drivers
  – Stubs
Scaffolding

• Test driver
  – A “main” program for running a test
    • May be produced before a “real” main program
    • Provide more control than the “real” main program
  – To drive program under test through test cases

• Test stub
  – Substitute for called functions/methods/objects

• Test harness
  – Substitutes for other parts of the deployed environment
  – E.g. Software simulation of a hardware device
Controllability & Observability

- Example: We want to automate tests,
  - But, interactive input provides limited control
  - Graphical output provides limited observability.

GUI input (MVC “Controller”)

Program Functionality

Graphical output (MVC “View”)
Controllability & Observability

• Solution: A design for automated test provides interfaces for control (API) and observation (wrapper on output)
Generic vs. Specific Scaffolding

• How general should scaffolding be?
  – We could build a driver and stubs for each test case.
  – Or at least factor out some common code of the driver and test management (e.g. JUnit)
  – Or further factor out some common support code, to drive a large number of test cases from data (as in DDSteps)
  – Or further generate the data automatically from a more abstract model (e.g. network traffic model)

• It’s a question of costs and re-use, just as for other kinds of software.
Test Oracles

- No use running 10,000 test cases automatically, if the results must be checked by hand.

- It’s a problem of ‘range of specific to general’, again
  - E.g. JUnit: Specific oracle (“assert”) coded by hand in each test case

- Typical approach
  - Comparison-based oracle with predicted output value
  - But, not the only approach
Comparison-based Oracle

- With a comparison-based oracle, we need predicted output for each input.
  - Oracle compares actual to predicted output, and reports failure if they differ.
  - Fine for a small number of hand-generated test cases
  - E.g. for hand-written JUnit test cases
Self-Checks as Oracles

- An oracle can also be written as self-checks.
  - Often possible to judge correctness without predicting results

- Advantages and limits: Usable with large, automatically generated test suites, but often only a partial check
  - E.g. structural invariants of data structures
  - Recognize many or most failures, but not all
Capture and Replay

• Sometimes there is no alternative to human input and observation.
  – Even if we separate testing program functionality from GUI, some testing of the GUI is required.

• We can at least cut repetition of human testing.

• Capture a manually run test case, and replay it automatically
  – With a comparison-based test oracle: behavior be same as previously accepted behavior
  – Reusable only until a program change invalidates it
  – Lifetime depends on abstraction level of input and output.
Summary

- Test automation aims to separate creative task of test design from mechanical task of test execution.
  - Enable generation and execution of large test suites
  - Re-execute test suites frequently (e.g. nightly or after each program change)

- Scaffolding: Code to support development and testing
  - Test drivers, stubs, harness, oracles
  - Ranging from individual, hand-written test case drivers to automatic generation and testing of large test suites
  - Capture/replay where human interaction is required
Chapter 18. Inspection
Chapter 19.
Program Analysis
Learning Objectives

- Understand how automated program analysis complements testing and manual inspection
  - Most useful for properties that are difficult to test

- Understand fundamental approaches of a few representative techniques
  - Lockset analysis
  - Pointer analysis
  - Symbolic testing
  - Dynamic model extraction

- Recognize the same basic approaches and design trade-offs in other program analysis techniques
Overview

- Automated program analysis techniques complement test and inspection in two ways:
  - Can exhaustively check some important properties
    - Which conventional testing is particularly ill-suited
  - Can extract and summarize information for test and inspection design
    - Replacing or augmenting human efforts

- Automated analysis
  - Replace human inspection for some class of faults
  - Support inspection by
    - Automating extracting and summarizing information
    - Navigating through relevant information
Static vs. Dynamic Analysis

- **Static analysis**
  - Examine program source code
    - Examine the complete execution space
    - But, may lead to false alarms

- **Dynamic analysis**
  - Examine program execution traces
    - No infeasible path problem
    - But, cannot examine the execution space exhaustively

- **Example:**
  - Concurrency faults
  - Memory faults
Summarizing Execution Paths

- Our aim is to find all program faults of a certain kind.
  - We cannot simply prune exploration of certain program paths as in symbolic testing.

- Instead, we must abstract enough to fold the state space down to a size that can be exhaustively explored.
  - Example: analyses based on finite state machines (FSM)
    - data values by states
    - operations by state transitions
  - The approaches taken in flow analysis and finite state verification
Memory Analysis

• Instrument program to trace memory access dynamically
  – Record the state of each memory location
  – Detect accesses incompatible with the current state
    • Attempts to access unallocated memory
    • Read from uninitialized memory locations
  – Array bounds violations:
    • Add memory locations with state unallocated before and after each array
    • Attempts to access these locations should be detected immediately
  – Example:
    • Purify
    • Garbage detector
Pointer Analysis

• Pointer variables are represented by a machine with three states:
  – invalid value
  – possibly null value
  – definitely not null value

• Deallocation triggers transition from non-null to invalid.
• Conditional branches may trigger transitions.
  – E.g. testing a pointer for non-null triggers a transition from possibly null to definitely non-null

• Potential misuse
  – Deallocation in possibly null state
  – Dereference in possibly null
  – Dereference in invalid states
A C Program with “Buffer Overflow”

```c
int main (int argc, char *argv[]) {
    char subject[] = "AndPlus+%26%2B+%0D%";
    char sentinel_post[] = "26262626";
    char *outbuf = (char *) malloc(10);
    int return_code;

    printf("First test, subject into outbuf\n");
    return_code = cgi_decode(subject, outbuf);
    printf("Original: %s\n", subject);
    printf("Decoded:  %s\n", outbuf);
    printf("Return code: %d\n", return_code);

    printf("Second test, argv[1] into outbuf\n");
    printf("Argc is %d\n", argc);
    assert(argc == 2);
    return_code = cgi_decode(argv[1], outbuf);
    printf("Original: %s\n", argv[1]);
    printf("Decoded:  %s\n", outbuf);
    printf("Return code: %d\n", return_code);
}
```

Output parameter of fixed length can overrun the output buffer.
Dynamic Memory Analysis with Purify

[I] Starting main

[E] ABR: Array bounds read in printf {1 occurrence}
   Reading 11 bytes from 0x00e74af8 (1 byte at 0x00e74b02 illegal)
   Address 0x00e74af8 is at the beginning of a 10 byte block
   Address 0x00e74af8 points to a malloc'd block in heap 0x00e70000
   Thread ID: 0xd64

...[E] ABR: Array bounds read in printf {1 occurrence}
   Reading 11 bytes from 0x00e74af8 (1 byte at 0x00e74b02 illegal)
   Address 0x00e74af8 is at the beginning of a 10 byte block
   Address 0x00e74af8 points to a malloc'd block in heap 0x00e70000
   Thread ID: 0xd64

...[E] ABWL: Late detect array bounds write {1 occurrence}
   Memory corruption detected, 14 bytes at 0x00e74b02
   Address 0x00e74b02 is 1 byte past the end of a 10 byte block at 0x00e74af8
   Address 0x00e74b02 points to a malloc'd block in heap 0x00e70000
   63 memory operations and 3 seconds since last-known good heap state
   Detection location - error occurred before the following function call
   printf [MSVCRT.dll]

... Allocation location
   malloc [MSVCRT.dll]

...[I] Summary of all memory leaks... {482 bytes, 5 blocks}

...[I] Exiting with code 0 (0x00000000)
   Process time: 50 milliseconds
[II] Program terminated ...
Lockset Analysis

- **Data races** are hard to reveal with testing.

- **Static analysis:**
  - Computationally expensive, and approximated

- **Dynamic analysis:**
  - Can amplify sensitivity of testing to detect potential data races
    - Avoid pessimistic inaccuracy of finite state verification
    - Reduce optimistic inaccuracy of testing
Dynamic Lockset Analysis

• Lockset discipline: set of rules to prevent data races
  – Every variable shared between threads must be protected by a mutual exclusion lock.
  – ....

• Dynamic lockset analysis detects violation of the locking discipline.
  – Identify set of mutual exclusion locks held by threads when accessing each shared variable.
  – INIT: each shared variable is associated with all available locks
  – RUN: thread accesses a shared variable
    • intersect current set of candidate locks with locks held by the thread
  – END: set of locks after executing a test
    = set of locks always held by threads accessing that variable
    • empty set for \( v \) = no lock consistently protects \( v \)
### Simple Lockset Analysis: An Example

<table>
<thead>
<tr>
<th>Thread</th>
<th>Program trace</th>
<th>Locks held</th>
<th>Lockset(x)</th>
</tr>
</thead>
<tbody>
<tr>
<td>thread A</td>
<td>lock(lck1)</td>
<td>{}</td>
<td>{lck1, lck2} INIT: all locks for x</td>
</tr>
<tr>
<td></td>
<td>x=x+1</td>
<td>{lck1}</td>
<td>lck1 held</td>
</tr>
<tr>
<td></td>
<td>unlock(lck1)</td>
<td>{}</td>
<td></td>
</tr>
<tr>
<td>thread B</td>
<td>lock(lck2)</td>
<td>{}</td>
<td>{lck2} lck2 held</td>
</tr>
<tr>
<td></td>
<td>x=x+1</td>
<td>{lck2}</td>
<td></td>
</tr>
<tr>
<td></td>
<td>unlock(lck2)</td>
<td>{}</td>
<td>Empty intersection → potential race</td>
</tr>
</tbody>
</table>
Lockset Analysis in Practice

- Simple locking discipline violated by
  - Initialization of shared variables without holding a lock
  - Writing shared variables during initialization without locks
  - Allowing multiple readers in mutual exclusion with single writers

```
Virgin
  write
  read/write/first thread

Exclusive
  write/new thread
  read/new thread

Shared
  read

Shared-Modified
  write

Delay analysis till after initialization (second thread)

Multiple writers report violations

Multiple readers single writer do not report violations
```
Extracting Behavior Model from Execution

• Behavior analysis can
  – Gather information from executing several test cases
  – And synthesize a model that characterizes those execution,
  – To the extent that they are the representative of other executions as well.

• Using behavioral models for
  – Testing : validate tests thoroughness
  – Program analysis : understand program behavior
  – Regression testing : compare versions or configurations
  – Testing of component-based software : compare components in different contexts
  – Debugging : Identify anomalous behaviors and understand causes
Summary

• Program analysis complements testing and inspection.
  – Addresses problems (e.g., race conditions, memory leaks) for which conventional testing is ineffective
  – Can be tuned to balance exhaustiveness, precision and cost (e.g., path-sensitive or insensitive)
  – Can check for faults or produce information for other uses (debugging, documentation, testing)

• A few basic strategies
  – Build an abstract representation of program states by monitoring real or simulated (abstract) execution
Part IV. Process
Chapter 20.
Planning and Monitoring the Process
Chapter 21.
Integration and Component-based Software Testing
Chapter 22.
System, Acceptance, and Regression Testing
Chapter 23.
Automating Analysis and Test
Chapter 24.
Documenting Analysis and Test